ON THE WEIGHT OF HALFSPACES OVER HAMMING BALLS*

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Abstract. For $S \subseteq \{0,1\}^n$, a Boolean function $f : S \rightarrow \{-1,1\}$ is a halfspace over $S$ if there exist $w \in \mathbb{R}^n$ and $\theta \in \mathbb{R}$ such that $f(x) = \text{sign}(w \cdot x - \theta)$ for all $x \in S$. We give bounds on the size of integer weights $w_1, \ldots, w_n \in \mathbb{Z}$ that are required to represent halfspaces over Hamming balls $S = \{x \in \{0,1\}^n : x_1 + \cdots + x_n \leq k\}$. Such weight bounds for halfspaces over Hamming balls have immediate consequences for the performance of learning algorithms in the common scenario of learning from very high-dimensional categorical examples which are such that only a small number of features are active in each example. We give upper and lower bounds on weight both for exact representation (when $\text{sign}(w \cdot x - \theta)$ must equal $f(x)$ for every $x \in S$) and for $\varepsilon$-approximate representation (when $\text{sign}(w \cdot x - \theta)$ may disagree with $f(x)$ for up to an $\varepsilon$ fraction of points $x \in S$). Our results show that extremal bounds for exact representation are qualitatively rather similar whether the domain is all of $\{0,1\}^n$ or the Hamming ball $\{0,1\}^n_{\leq k}$, but extremal bounds for approximate representation are qualitatively very different between these two domains.

Key words. linear threshold functions, halfspaces, Boolean functions, Boolean hypercube

AMS subject classification. 68R05

DOI. 10.1137/120868402

1. Introduction. Let $S$ be a subset of the Boolean hypercube $\{0,1\}^n$. We say that a Boolean function $f : S \rightarrow \{-1,1\}$ is a halfspace over $S$ if there exist $w \in \mathbb{R}^n$ and $\theta \in \mathbb{R}$ such that $f(x) = \text{sign}(w \cdot x - \theta)$ for all $x \in S$. The pair $(w,\theta)$ is an integer representation of $f$ if $w \in \mathbb{Z}^n$. The weight of an integer representation is $\max_{x \in S} |w_x|$. The weight of a halfspace $f$ over $S$ is the smallest weight of any integer representation which computes $f$ correctly on all $x \in S$.

Many researchers have studied the weight of halfspaces over the entire Boolean cube (corresponding to taking $S = \{0,1\}^n$); see, e.g., [15, 14, 17, 18, 16, 19, 13, 9, 1, 22, 4]. Upper and lower bounds have been obtained both for exact representation, as described above, and for a relaxed scenario in which the integer-weight halfspace $\text{sign}(w \cdot x - \theta)$ need only $\varepsilon$-approximate the function $f$ (i.e., we allow $\Pr_{x \in S} [\text{sign}(w \cdot x - \theta) \neq f(x)]$ to be at most $\varepsilon$ for some given approximation parameter $\varepsilon > 0$). We describe these previous results in detail in section 1.1.

In this paper we give a detailed study of the weight of halfspaces, both exact and approximate, over Hamming balls of radius $k$; i.e., we study halfspaces over the domain

$$S = \{0,1\}^n_{\leq k} = \{x \in \{0,1\}^n : x_1 + \cdots + x_n \leq k\}.$$

Motivation. In machine learning scenarios involving categorical (as opposed to numerical) data, the most common way to represent an unlabeled example is as a vector in $\{0,1\}^n$, where each coordinate corresponds to a binary feature and a value of 1 indicates that the feature is active in the example. In many modern machine learning problems, the set of all possible features is extremely large (e.g., the set of
all possible words) but each example has only a small number of active features (e.g., the set of words in a given search query). In such a setting, the space of all possible examples is contained in a Hamming ball \( \{0, 1\}^n_{\leq k} \), where \( k \ll n \). A natural question is what types of learning algorithms are particularly well suited to this sort of data.

In machine learning, various notions of the “margin” of a binary classifier on an input formalize in different ways the extent to which the classifier makes a clear-cut prediction on that input [2, 21]. The margin of a classifier on a set of inputs is taken to be the minimum margin over all inputs in the set. Upper and lower bounds on the margin of a halfspace classifier \( f \) over a set of inputs are known to be closely related to the weight of \( f \) [11, 5, 21, 23]. Thus, bounds on the weights of halfspaces provide a way to bound their margins. Since halfspaces play a fundamental role in machine learning, and the margin of a halfspace \( H \) is an important measure of the difficulty of learning \( H \), we are naturally motivated to understand the weight of halfspaces over Hamming balls, as an initial step toward understanding the impact of sparsity in feature vectors on learning complexity.

### 1.1. Previous work and our results

In this section we review prior work on the weight of halfspaces (all of the previous work that we are aware of deals with halfspaces over the entire Boolean cube \( \{0, 1\}^n \)), and we state our results for halfspaces over the Hamming ball \( \{0, 1\}^n_{\leq k} \).

**Prior work on exact representation of halfspaces over \( \{0, 1\}^n \).** It has been known at least since the 1960s [15] that every halfspace over \( \{0, 1\}^n \) has weight at most \( n^{O(n)} \) (this fact has been rediscovered several times; see, e.g., [10, 17]). Since there are \( 2^{\Omega(n^2)} \) halfspaces over \( \{0, 1\}^n \) a counting argument shows that there exist halfspaces over \( \{0, 1\}^n \) that require weight \( 2^{\Omega(n)} \), and specific halfspaces that require weight \( 2^{\Omega(n)} \) have been known for decades [14, 8]. H˚astad [9] exhibited a specific halfspace that has weight \( n^{\Omega(n)} \), and his construction was subsequently refined in [1]. So the weight of exact representations of halfspaces over all of \( \{0, 1\}^n \) is by now quite well understood.

**Our results on exact representation of halfspaces over \( \{0, 1\}^n_{\leq k} \).** We give an essentially complete picture of the weight of halfspaces over Hamming balls \( \{0, 1\}^n_{\leq k} \) for all values of \( k \). First, it is easy to see that for \( k \in \{0, 1\} \) every halfspace over \( \{0, 1\}^n_{\leq k} \) has an integer representation of weight 1. For \( k = 2 \), by analyzing a greedy construction we show (Theorem 2.2) that every halfspace over \( \{0, 1\}^n_{\leq 2} \) has weight \( O(n) \), and we observe that a simple explicit halfspace has weight \( \Theta(n) \).

Things get more interesting beyond \( k = 2 \). Using a linear programming argument, we show (Theorem 2.1) that for every \( k \geq 3 \), every halfspace over \( \{0, 1\}^n_{\leq k} \) has an integer representation of weight \( (k + 2)^{(n+1)/2} \), and we show that already for \( k = 3 \) there is a simple explicit halfspace for which any integer representation must have weight \( 2^{\Omega(n)} \). Our main lower bound result for exact representation (Theorem 3.1) is a general lower bound showing that for every \( k \geq 3 \), there is an explicit halfspace over \( \{0, 1\}^n_{\leq k} \) that requires integer weight \( k^{\Omega(n)} \). This is established via a construction that carefully combines H˚astad’s halfspace [9] with a “decision list”-type construction. Our lower bound shows that our upper bound on the weight of halfspaces over \( \{0, 1\}^n_{\leq k} \) is essentially the best possible.

**Prior work on approximation over \( \{0, 1\}^n \).** The lower bound of [9] immediately implies that there is an \( n \)-variable halfspace \( f \) over \( \{0, 1\}^n \) which is such that any \( \varepsilon \)-approximating halfspace \( \text{sign}(w \cdot x - \theta) \) (i.e., \( w \) satisfies \( \Pr_{x \in \{0, 1\}^n}[\text{sign}(w \cdot x) \neq f(x)] \)
Our results on approximation over \( \{0, 1\}^n \). We study the weight required to \( \varepsilon \)-approximate halfspaces over \( \{0, 1\}^n \), i.e., given a halfspace \( f \) we now allow the integer-weight halfspace \( \text{sign}(w \cdot x - \theta) \) to disagree with \( f(x) \) on an \( \varepsilon \) fraction of all points in \( \{0, 1\}^n \). (For the informal discussion here \( k \) should be viewed as “small” compared to \( n \); precise bounds on \( k \) are given in the actual detailed theorem statements.) As our main positive result (Theorem 5.1), we show that for every \( f \), statements.) As our main positive result (Theorem 5.1), we show that for every halfspace \( f \) over \( \{0, 1\}^n \) there is a halfspace that \( \varepsilon \)-approximates \( f \) and has integer weights each of which is at most \( k^{O(k/\varepsilon)} \), independent of \( n \). This proof combines linear programming arguments with upper bounds on the edge boundary of monotone Boolean-valued functions over the discrete domain \( \{1, \ldots, t\}^k \).

As our main negative result (Theorem 6.1), we show that for any constant \( k \geq 3 \) there is a simple explicit halfspace \( f \) (the “decision list” halfspace, which we denote \( DL \)) which is such that any \( \varepsilon \)-approximator of \( f \) over \( \{0, 1\}^n \) must have weight \( k^{\Omega(1/\varepsilon^{1/(k-1))}} \). This shows that an inverse exponential dependence on \( 1/\varepsilon \) is necessary in any upper bound for \( \{0, 1\}^n \) when \( k = O(1) \), in contrast to the \( \sqrt{n \cdot (1/\varepsilon)^{O(\log(1/\varepsilon))}} \) upper bound over all of \( \{0, 1\}^n \) recently established in [3].

Finally, we give a detailed analysis of the specific “decision list” halfspace \( DL \) and show (Theorem 7.1) that for this particular function the general weight upper bound of Theorem 5.1 can be strengthened to \( k^{O(k/\sqrt{\varepsilon})} \). This shows that strengthening the analysis of the \( DL \) function that is given in Theorem 6.1 will not be enough to improve that lower bound to match the general upper bound of Theorem 5.1.

Discussion. Our results show that (as long as \( k \geq 3 \)) the extremal bounds on the weights required for exact representation of halfspaces are fairly similar whether the domain is \( \{0, 1\}^n \) or \( \{0, 1\}^n \); in the former case the “right” weight bound is \( k^{\Theta(n)} \), while in the latter case it is \( n^{\Theta(n)} \). For \( \varepsilon \)-approximate representation, though, our results show that there are two interesting qualitative differences between the “right” weight bounds for the two domains. First, our \( k^{O(1/\varepsilon)} \) upper bound (independent of \( n \) for \( \{0, 1\}^n \)) stands in contrast with the \( \Omega(\sqrt{n}) \) lower bound of [22] for \( \{0, 1\}^n \); so for Hamming balls no dependence on \( n \) is necessary in the weights, whereas for the Boolean cube a polynomial dependence is required. Second, our \( k^{\Omega(1/\varepsilon^{1/(k-1))}} \) lower bound shows that for any fixed constant \( k \), some halfspaces over \( \{0, 1\}^n \) require any \( \varepsilon \)-approximator to have weights that are \text{exponential} in \( 1/\varepsilon \). This is in sharp contrast with the recent [3] upper bound, which shows that over \( \{0, 1\}^n \) it is always possible to construct an \( \varepsilon \)-approximating halfspace with integer weights that are only quasi-polynomial in \( 1/\varepsilon \). Intuitively, this disparity may be viewed as a consequence of the “nice structure” of the uniform distribution over \( \{0, 1\}^n \) (with attractive properties such as independence between coordinates, sub-Gaussian tails for linear forms \( w \cdot x \), etc.) which is not present in the uniform distribution over \( \{0, 1\}^n \).

Preliminaries. Note that under the correspondence \(-1 \leftrightarrow 0\), \( 1 \leftrightarrow 1\) an integer-weight halfspace \( \text{sign}(w \cdot x - \theta) \) over the hypercube \( \{-1, 1\}^n \) corresponds to an integer-weight halfspace \( \text{sign}(2w \cdot x - (\theta + w_1 + \cdots + w_n)) \) over the hypercube \( \{0, 1\}^n \). So we may work either over the Hamming ball \( \{0, 1\}^n \) = \( \{x \in \{0, 1\}^n : x_1 + \cdots + x_k \leq k\} \) of the
0/1 hypercube or over the Hamming ball \(\{-1,1\}^n_{\leq k} = \{x \in \{-1,1\}^n : x_1 + \cdots + x_k \leq n - 2k\}\) of the +1/−1 hypercube; weight bounds obtained for one domain will carry over to the other one with at most a factor of 2 difference. Similarly we may also work over \(\{-1,1\}^n_{\geq n-k} = \{x \in \{-1,1\}^n : x_1 + \cdots + x_k \geq n - 2k\}\); sometimes this will be the most convenient.

Some more useful observations: If \(\text{sign}(w \cdot x - \theta)\) is a halfspace with integer coefficients over any subset \(S \subseteq \{-1,1\}^n\) or \(S \subseteq \{0,1\}^n\), then it is easy to see that without loss of generality we may modify the threshold \(\theta\) to be of the form (integer + \(\frac{1}{2}\)). We also note that if \(\text{sign}(w \cdot x - \theta)\) is an integer-weight halfspace with such a threshold that computes a function \(f\) over \(\{-1,1\}^n_{\leq k}\), then \(\text{sign}(w \cdot x + \theta)\) is a halfspace of the same weight computing \(f\) over \(\{-1,1\}^n_{\leq k}\); so to bound the weight of \(f\) over \(\{-1,1\}^n_{\leq k}\) it is enough to bound the weight of \(-f\).

Finally, we establish some useful notation. We denote \{1,...,n\} by \([n]\). For \(i \in [n]\) we write \(e_i\) to denote the unit vector in \(\mathbb{R}^n\) whose only nonzero entry is a 1 in the \(i\)-th coordinate. We let \(DL(x)\) denote the “decision list” halfspace over \(\{0,1\}^n\) that is defined as follows: \(DL(x)\) equals \((-1)^i\), where \(i\) is the largest index such that \(x_i = 1\). If \(x\) is the all-0 string \((0)^n\), then \(DL(x) = 1\). To see that \(DL(x)\) is a halfspace, we observe that it can be represented as \(DL(x) = \text{sign}(\sum_{i=1}^n (-2)^i x_i, 1)\). The function is called the “decision list” halfspace because it computes the decision list “if \(x_n = 1\), then output \((-1)^n\), else if \(x_{n-1} = 1\), then output \((-1)^{n-1}\), else … .”

2. Upper bounds for exact representation. We start with a general upper bound. The proof is a straightforward modification of standard integer-weight upper bound arguments for halfspaces over \(\{0,1\}^n\) (see, e.g., [15, 9]) adapted to the domain \(\{0,1\}^n_{\leq k}\).

**Theorem 2.1.** For \(3 \leq k \leq n\), every halfspace over \(\{0,1\}^n_{\leq k}\) has weight at most \((k + 2)^{(n+1)/2}\).

**Proof.** Fix \(f\) to be any halfspace over \(\{0,1\}^n_{\leq k}\). Each point \(x\) in \(\{0,1\}^n_{\leq k}\) with \(f(x) = y \in \{-1,1\}\) provides a linear constraint
\[y(w_1 x_1 + \cdots + w_n x_n + w_{n+1}) \geq 1\]
over the weights \(w_1, \ldots, w_{n+1}\) which define the halfspace \(f(x) = \text{sign}(w_1 x_1 + \cdots + w_n x_n + w_{n+1})\). Since \(f\) is a halfspace the above system of \(\sum_{j=0}^k \binom{n}{j}\) linear inequalities over variables \(w_1, \ldots, w_{n+1}\) is feasible. A standard result in the theory of linear programming (see, e.g., [15, 9]) implies that there is a subset of \(n+1\) of the above inequalities which is such that if each inequality is replaced with an equality, the resulting set of \(n+1\) equalities defines a unique weight vector \((w_1, \ldots, w_{n+1}) \in \mathbb{R}^{n+1}\) which is a feasible solution to the entire set of \(\sum_{j=0}^k \binom{n}{j}\) inequalities. In other words, there is a representation \(\text{sign}(w \cdot x + w_{n+1})\) computing \(f\) where \((w_1, \ldots, w_{n+1}) \in \mathbb{R}^{n+1}\) is the solution to a linear system
\[Aw = b,\]
where \(b \in \{-1,1\}^{n+1}\) and \(A\) is an \((n+1) \times (n+1)\) 0/1 matrix in which the first \(n\) entries of each row have at most \(k\) ones and the last entry is 1. Let \(\frac{\det(A)}{\det(A_i)}\) be the expression for a solution \(w_i\) using Cramer’s rule. Since scaling the components of \(w\) by the same constant factor does not affect the behavior of \(f\), setting each \(w_i = \det(A_i)\) also works. Fix an arbitrary \(i\), let \(B = A_i\), and let \(B_1, \ldots, B_{n+1}\) be the rows of \(B\). Hadamard’s inequality (see, e.g., [6, p. 233]) gives \(\det(B) \leq \prod_{j=1}^{n+1} ||B_j||\), where
\[ \|B_j\| \] denotes the 2-norm of \( B_j \) viewed as a vector in \( \mathbb{R}^{n+1} \). Let \( \ell_j \leq k + 2 \) be the number of nonzero components in \( B_j \); since these components are all \( \pm 1 \), we have \( \|B_j\| = \sqrt{\ell_j} \), so that \( \det(B) \leq \prod_{j=1}^{n+1} \sqrt{\ell_j} \leq (k + 2)^{(n+1)/2} \). So \( f \) can be realized using integer weights of at most this magnitude.

We note that the proof given above actually holds for all \( k \geq 1 \) (not just \( k \geq 3 \) as in the theorem statement), but much stronger bounds are possible for \( k = 1, 2 \). For \( k = 1 \), it is easy to see that every halfspace over \( \{0, 1\}_{\leq 1} \) has an integer representation of weight 1. For \( k = 2 \) Theorem 2.1 only gives an upper bound that is exponential in \( n \), but the true extremal value for \( k = 2 \) is actually linear in \( n \).

**Theorem 2.2.** Every halfspace \( f \) over \( \{0, 1\}_{\leq 2} \) has weight \( O(n) \).

Before giving the proof, here is some high-level intuition. Since we are working over \( \{0, 1\}_{\leq 2} \), intuitively in order to set the weight \( v_j \) of variable \( x_j \) correctly the “only constraint that matters” is how many of the other \( n - 1 \) variables \( x_i \) are such that \( f(e_i + e_j) = 1 \). The proof shows that a suitable greedy approach of setting the weights can satisfy all these constraints taking all the weights to be \( O(n) \) in absolute value.

**Proof of Theorem 2.2.** Since \( f \) is a halfspace over \( \{0, 1\}_{\leq 2} \), it has some representation as \( f(x) = \text{sign}(w \cdot x - \theta) \), where \( w_1, \ldots, w_n, \theta \) are real numbers. We will use this representation to construct an integer-weight representation \( \text{sign}(v \cdot x - \theta') \) that agrees with \( f \) on all points in \( \{0, 1\}_{\leq 2} \) and where each \( |v_i| \leq O(n) \).

By negating \( f \) if necessary (which does not change the integer weight required for a representation) we may assume that \( f(0^n) = -1 \). This means that \( \text{sign}(-\theta) = -1 \), and thus we have \( \theta > 0 \).

We may suppose without loss of generality that \( w_1 < \cdots < w_n \) and all \( n \) weights \( w_1, \ldots, w_n \) are nonzero (since if the weights do not satisfy these conditions they can be reordered and perturbed to satisfy them). We note that if \( w_n < 0 \), then every input \( x \in \{0, 1\}_{\leq 2} \) (and indeed every input in \( \{0, 1\}^n \)) has \( w \cdot x \leq 0 < \theta \); in this case \( f \) is the constant \( -1 \) function and \( f \) trivially has a representation of weight 0. Thus we assume going forth that \( w_n > 0 \).

Let \( \ell \in \{1, \ldots, n\} \) be such that \( w_{\ell-1} < w_\ell \) (so \( \ell = 1 \) if \( w_1 > 0 \)). Now,

- let \( w' \in \mathbb{R}^{n+1} \) be \( (w_1, \ldots, w_{\ell-1}, 0, w_\ell, \ldots, w_n) \);
- for each \( x \in \{0, 1\}_{\leq 2}^n \), let \( x' \in \{0, 1\}_{\leq 2}^{n+1} = (x_1, \ldots, x_{\ell-1}, 0, x_\ell, \ldots, x_n) \);
- for each \( x \in \{0, 1\}_{\leq 2}^n \), let \( x' \in \{0, 1\}_{\leq 2}^{n+1} = (x_1, \ldots, x_{\ell-1}, 1, x_\ell, \ldots, x_n) \);
- when \( x = 0^n \), let \( x' \in \{0, 1\}_{\leq 2}^{n+1} \) be \((0, \ldots, 0)\).

Note that, for all \( x \in \{0, 1\}_{\leq 2}^n \), \( \text{sign}(w' \cdot x' - \theta) = \text{sign}(w \cdot x - \theta) \), and, for all \( x \) except \( 0^n \), \( x' \) has exactly two ones. Furthermore, if we have a weight vector \( v \in \mathbb{R}^{n+1} \) such that \( v_\ell = 0 \), if we define \( \hat{v} \in \mathbb{R}^n \) by \( \hat{v} = (v_1, \ldots, v_{\ell-1}, v_{\ell+1}, v_{n+1}) \), then, for all \( x \in \{0, 1\}_{\leq 2}^n \) and all real \( \theta \), we have \( \text{sign}(v \cdot x' - \theta) = \text{sign}(\hat{v} \cdot x - \theta) \). So, our problem reduces to the problem of finding a vector \( v \in \mathbb{R}^{n+1} \) with small integer weights for which \( v_\ell = 0 \) and there is a \( \theta' \) such that

\[
\text{sign}(v \cdot x - \theta') = \text{sign}(w' \cdot x - \theta)
\]

for all \( x \in \{0^{n+1}\} \cup \{0, 1\}_{\leq 2}^{n+1} \).

Now let us define an \((n + 1) \times (n + 1)\) matrix \((M(i,j))_{i,j \in \{1, \ldots, n+1\}}\) with entries in \( \{-1, 1\} \) as follows. The matrix \( M \) will be symmetric, i.e., \( M(i,j) = M(j,i) \). It will also be monotone nondecreasing within each row and column, i.e., for each value \( i \), the string \( M(i,1) \ldots M(i,n+1) \) will be of the form \((-1)^r(1)^{n+1-r} \) for some \( r \in \{0, \ldots, n+1\} \); i.e., the first \( r \) characters will be \(-1 \) and the remaining characters \( 1 \). Here is how \( M \) is defined:
For \( \{i, j\} \subset \{1, \ldots, n + 1\} \) we have \( M(i, j) = 1 \) if and only if \( \text{sign}(w' \cdot (e_i + e_j)) = 1 \).

- Define \( M(\ell, \ell) = -1 \) (recall that \( f(0^n) = -1 \)) and define the other diagonal values, \( M(i, i) \) for \( i \neq \ell \), as follows. For \( i > 1 \) simply set \( M(i, i) = 0 \) for \( i \neq \ell \). For \( i = 1 \) set \( M(1, 1) = -1 \). For \( i > 1 \) set \( M(1, i) = 1 \).

For example, if

\[
M = \begin{pmatrix}
-1 & -1 & -1 & -1 & 1 & 1 \\
-1 & -1 & -1 & -1 & 1 & 1 \\
-1 & -1 & 1 & 1 & 1 & 1 \\
-1 & -1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & 1 & 1 \\
\end{pmatrix}
\]

It is easy to check that, in general, the matrix \( M \) is indeed symmetric. By virtue of the fact that \( w_1 < \cdots < w_{\ell-1} < 0 < w_{\ell+1} < \cdots < w_n \), we have that \( M \) is monotone increasing within each row and column. Finally, the construction of \( M \) ensures that it faithfully reflects the structure of \( f \) over \( \{0, 1\}_{\leq 2}^n \), in the following sense. Suppose we can define weights \( v_1 \leq \cdots \leq v_{n+1} \) and a threshold \( \theta' \) with \( v_\ell = 0 \) such that

\[
M(i, j) = 1 \quad \text{if and only if} \quad v_i + v_j \geq \theta'.
\]

Then the halfspace

\[
\text{sign}(v_1 x_1 + \cdots + v_{\ell-1} x_{\ell-1} + v_{\ell+1} x_{\ell+1} + \cdots + v_{n+1} x_{n+1} - \theta')
\]

correctly computes \( f \) over \( \{0, 1\}_{\leq 2}^n \) and therefore correctly solves the original problem. (In fact (2.2) is stronger than what is needed—all of the correct classifications are already enforced by the off-diagonal elements, with the exception of \( 0^n \), whose correct classification is enforced by the constraint associated with \( M(\ell, \ell) \).

In the rest of the proof we will construct the desired \( v_1, \ldots, v_{n+1} \) satisfying (2.2) where

\[
v_1 \leq \cdots \leq v_{\ell-1} \leq v_\ell = 0 \leq v_{\ell+1} \leq \cdots \leq v_{n+1},
\]
each \( v_i \) is an integer, and each \( v_i \) satisfies \( |v_i| \leq O(n) \).

Going forth, the following notation will be useful: we write \( M_i \) to denote the \( i \)th row of \( M \), which we view as an \((n + 1)\)-character string \( M(i, 1), \ldots, M(i, n + 1) \) over the alphabet \( \{-1, 1\} \), and \( i \), of course, the same as the \( i \)th column of \( M \).

We may assume that \( M \) is not the \((n + 1) \times (n + 1)\) identically \(-1\) matrix (since if it is, then \( f \) is the constant \(-1\) function over \( \{0, 1\}_{\leq 2}^n \), so in particular the bottom right entry \( M(n + 1, n + 1) \) equals 1. On the other hand, we know that the \( M(\ell, \ell) \) entry is \(-1\). Since \( M \) is monotone increasing within each row and column, and is
symmetric, the only way that $M$ could have all its rows $M_1 = \cdots = M_{n+1}$ equal to each other is if $M$ were either the identically $+1$ or identically $-1$ matrix. Since $M$ is neither of these matrices, there are at least two distinct rows in $M$.

The weights $v_1, \ldots, v_{n+1}$ are constructed as follows. We partition $\{1, \ldots, n+1\}$ into $2 \leq A \leq n + 1$ intervals $I_1, \ldots, I_A$ in the following way. The interval $I_1$ is $\{1, \ldots, i_1\}$, where $i_1$ is such that rows $1, \ldots, i_1$ satisfy $M_1 = \cdots = M_{i_1} \neq M_{i_1+1}$. Let $j_1$ be such that $M_1 = \cdots = M_{i_1} = (-1)^{n+1-j_1}(1)^{j_1}$. Then interval $I_2$ is $\{i_1 + 1, \ldots, i_2\}$, where similarly $i_2$ is such that $M_{i_1+1} = \cdots = M_{i_2} \neq M_{i_2+1}$. As before $j_2$ denotes the value such that $M_{i_1+1} = \cdots = M_{i_2} = (-1)^{n+1-j_2}(1)^{j_2}$ (note that $j_2 > j_1$). Continuing in this way we get intervals $I_1, \ldots, I_A$ and values $0 \leq j_1 < \cdots < j_A \leq n + 1$, where the right endpoint of $I_A$ is $n + 1$. If $a < b$ are both in the same interval $I_i$, then our construction will assign the same weight to $v_a$ and $v_b$.

Returning to the example shown in (2.1), we have

- $I_1 = \{1, 2\}$, $I_2 = \{3\}$, $I_3 = \{4, 5\}$, $I_4 = \{6, 7\}$,
- $i_1 = 2$, $i_2 = 3$, $i_3 = 5$, $i_4 = 7$, and
- $j_1 = 2$, $j_2 = 4$, $j_3 = 5$, $j_4 = 7$.

Let $t$ be the index for which $\ell \in I_t$. Fix any index $i \in \{1, \ldots, A\}$ and consider any element $a \in I_i$. We have that $M(a, n + 1 - j_i) = -1$, while $M(a, n + 2 - j_i) = 1$.

The idea of our construction is that we will maintain

\[(2.4) \quad v_a + v_{n+1-j_i} = A - 2t \quad \text{and} \quad v_a + v_{n+2-j_i} = A - 2t + 1.\]

Together with (2.3) this ensures that (2.2) holds as required, taking $\theta' = A - 2t + 1/2$.

We claim that (2.4), along with $v_t = 0$, is satisfied if, for each interval $I_i$, the following holds:

\[(2.5) \quad \forall a \in I_i, \quad v_a = i - t.\]

Consider the case that $i = 1$, and fix an $a \in I_1$. Recall $M(a, j) = -1$ for $j = 1, \ldots, n + 1 - j_1$, and $M(a, j) = 1$ from $j = n + 2 - j_1$ on; in particular, $M(a, n + 2 - j_1) = 1$.

The monotonicity of $M$ implies that columns $n + 2 - j_1$ through $n + 1$ consist of all 1’s, and since $M(a, n + 1 - j_1) = -1$, this is not true of column $n + 1 - j_1$. Since $M$ is symmetric, rows $n + 2 - j_1$ through $n + 1$ consist of all 1’s, and row $n + 1 - j_1$ does not. Thus $I_A = \{n + 2 - j_1, \ldots, n + 1\}$, so, referring back to (2.5), we have

\[v_{n+2-j_1} = A - t,\]

and since $v_{n+1-j_1} \in I_{A-1}$, we have

\[v_{n+1-j_1} = A - 1 - t.\]

Since $v_a = 1 - t$, we have that (2.4) holds when $i = 1$.

This pattern continues for $i = 2, 3, \ldots$. Using induction, we can see that, for each $i$, the boundary between $I_{A-i+1}$ and $I_{A-i}$ is between $n + 2 - j_i$ and $n + 1 - j_i$, so

\[v_{n+1-j_i} = A - t - i \quad \text{and} \quad v_{n+2-j_i} = A - t + 1 - i,\]

which, since $v_a = i - t$, implies (2.4), and therefore (2.2).

We have constructed $v_1, \ldots, v_{n+1}$ that satisfy (2.3) where each $v_i$ is an integer. It follows easily from the construction that each $|v_i|$ is at most $O(n)$, and the theorem is proved.  \[\square\]
We note that for odd $n$ the decision list halfspace $DL(x) = \text{sign}(\sum_{i=1}^{n} (-2)^i x_i)$ requires integer weight at least $(n-1)/2$ over $\{0,1\}_{\leq 2}^n$, and thus the $O(n)$ upper bound of Theorem 2.2 is tight up to a constant factor. To see this, suppose that $\text{sign}(v \cdot x - \theta)$ has integer weights and computes $DL$ correctly over $\{0,1\}_{\leq 2}^n$. By considering inputs of the form $e_i$, where $i$ ranges from 1 to $n$, we see that $v_i \geq \theta$ for $i$ even and $v_i < \theta$ for $i$ odd. By considering inputs of the form $e_i + e_{i+1}$ we see that $v_1 > v_3 > v_5 > \cdots > v_n$ and $v_2 < v_4 < v_6 < \cdots < v_{n-1}$, so there are $n$ distinct integer weights, and the largest magnitude weight must be at least $(n - 1)/2$ as claimed.

3. Lower bounds for exact representation. In this section we give lower bounds on the weight required to exactly represent various halfspaces over $\{-1,1\}_{\leq k}^n$ for $k \geq 3$. We first note that simple counting arguments do not give very good lower bounds. Let $N(n, k)$ denote $\sum_{i=0}^{k} \binom{n}{i}$, the number of points in $\{-1,1\}_{\leq k}^n$ (note that $N_k \leq (en/k)^k$). Since the VC dimension of halfspaces over $\{-1,1\}_{\leq k}^n$ is known to be $n+1$, the Sauer–Shelah lemma [20, 24] says that there are at most

$$\sum_{j=0}^{n+1} \binom{N_k}{j} \leq \sum_{j=0}^{n+1} \binom{(en/k)^k}{j} \leq \left(\frac{e(en/k)^k}{n+1}\right)^{n+1}$$

halfspaces over $\{-1,1\}_{\leq k}^n$. A standard counting argument says that if there are more than $C^n$ halfspaces over a given domain $S \subseteq \{-1,1\}_{\leq k}^n$, then some halfspace over $S$ must require integer weight $\Omega(C)$. So the strongest weight lower bound that can be obtained from this kind of counting argument is $O((en/k)^k/n)$. This is actually quite weak; we will see that much stronger lower bounds can be obtained for explicit functions.

An exponential lower bound for a simple function. We now observe that even for $k = 3$ a simple halfspace gives an exponential lower bound.

Observation 1. The function $DL(x)$ has weight $2^{O(n)}$ over $\{0,1\}_{\leq 3}^n$.

Proof. Let $\text{sign}(v \cdot x - \theta)$ be a representation of $DL$ over $\{0,1\}_{\leq 3}^n$. We may assume $\theta$ is of the form $(\text{integer} + 1/2)$ so its magnitude is at least $1/2$.

Since $DL(0^n) = \text{sign}(0 - \theta)$ is $+1$ we have that $\theta < 0$. Writing each $v_i$ as $w_i \theta$, we may divide through by $|\theta|$ and reexpress $\text{sign}(v \cdot x - \theta)$ as $\text{sign}(w \cdot x + 1)$. Here the $w_i$’s may not be integers, but since $|\theta| \geq 1/2$ it suffices to show that $|w_n| = 2^{O(n)}$.

Since $DL(e_j) = -1$ for $j$ odd we have $w_j < -1$ for $j$ odd, and since $DL(e_{k-1} + e_k) = 1$ for $k$ even we have $w_k \geq -w_{k-1} - 1$ and thus $w_k > 0$ for even $k$. For even $k \geq 4$, since $DL(e_k + e_{k-1} + e_{k-3}) = 1$ we have

$$|w_k| = w_k \geq -w_{k-1} - w_{k-3} - 1 = |w_{k-1}| + |w_{k-3}| - 1 \quad \text{for even } k \geq 4.$$  

For odd $k \geq 5$, since $DL(e_k + e_{k-1} + e_{k-3}) = -1$ we have $w_k < -w_{k-1} - w_{k-3} - 1$, and since $w_k$ is negative for odd $k$ and positive for even $k$, this means

$$|w_k| > |w_{k-1}| + |w_{k-3}| + 1 \quad \text{for odd } k \geq 5.$$  

An easy induction using the inequalities (3.1) and (3.2) and the initial condition $w_j < 1$ for $j$ odd gives that $|w_n| = 2^{O(n)}$. □

Main lower bound for exact representation. Observation 1 gives an exponential lower bound, but in general it does not match the $k^{O(n)}$ upper bound provided by Theorem 2.1. As our main lower bound result for exact representation we match
the upper bound of Theorem 2.1 (up to an absolute constant in the exponent) and prove the following.

**Theorem 3.1.** Let $k$ be an integer of the form $k = 2^l$, and let $n = rk + 1$ for some integer $r$. There is a halfspace $G$ (defined explicitly below) over $\{-1, 1\}^n_{\geq n-2k-1}$ for which the weight of any integer representation over $\{-1, 1\}^n_{\geq n-2k-1}$ is at least $2^{(n \log k)/2 - O(n)}$, i.e., $k^{O(n)}$.

We recall that in [9] Håstad gave an explicit halfspace over $\{-1, 1\}^k$ and proved that its weight over $\{-1, 1\}^k$ is $k^{\Theta(k)}$. Our construction builds on his construction; indeed our $n = (rk + 1)$-variable halfspace may be viewed as $r$ copies of Håstad’s halfspace “concatenated” in a careful way (the exact meaning of this will be clearer when we describe our construction in detail below).

**Setup.** First some notational preliminaries: Since $k = 2^l$ we may view a $k$-bit string as a function from $\{-1, 1\}^l$ to $\{-1, 1\}$, where an index $j \in \{0, \ldots, k-1\}$ is interpreted as an $\ell$-bit vector. To keep the notation clean, we will refer to $j \in \{0, \ldots, k-1\}$ and its $\ell$-bit binary representation interchangeably. For $f$ a $k$-bit string and $j \in \{0, \ldots, k-1\}$ we write $f(j)$ to denote the $j$th coordinate of such a string (or the function $f$ applied to $j$’s $\ell$-bit representation). For $f, g \in \{-1, 1\}^k$ we write $(f, g)$ to denote the inner product $\sum_{j=0}^{k-1} f(j)g(j)$. Note that for $f, g \in \{-1, 1\}^k$ we have $|f(g)| \leq k$.

Following the notation from [9], for $\alpha \subseteq [\ell] = \{1, \ldots, \ell\}$ let $\varphi_\alpha$ denote the parity function $\varphi_\alpha(x) = \prod_{i \in \alpha} x_i$ over the variables in $\alpha$. Again following [9], let $\alpha_0, \ldots, \alpha_{k-1}$ be an ordering of subsets of $[\ell]$ such that $|\alpha_i| \leq |\alpha_{i+1}|$ and the symmetric difference $\alpha_i \Delta \alpha_{i+1}$ always satisfies $|\alpha_i \Delta \alpha_{i+1}| \leq 2$. Note that $\alpha_0$ is the empty set and thus $\varphi_{\alpha_0}$ is the $k$-bit string consisting of all 1’s, while for each $j = 1, \ldots, k-1$ we have that $\varphi_{\alpha_j}$ is a $k$-bit string with exactly half of its entries $-1$.

Writing $f : \{-1, 1\}^\ell \to \{-1, 1\}$ in terms of its Fourier representation as $f(j) = \sum_{\alpha \subseteq [\ell]} f(\alpha)\varphi_\alpha(j)$ we see that $(f, \varphi_{\alpha_i})$ equals $k\hat{f}(\alpha_i)$, so we may view each inner product $(f, \varphi_{\alpha_i})$ as a scaled Fourier coefficient of $f$.

For $f \in \{-1, 1\}^n$ we decompose $f$ by writing it as $(b, f^1, \ldots, f^r)$, where $b \in \{-1, 1\}$ and each $f^i$ is a $k$-bit string. We sometimes refer to $f^i$ as the “$i$th block” of $f$ and write $f(i)$ to denote the $i$th coordinate of the $i$th block of $f$.

**The construction.** Let $G : \{-1, 1\}^n_{\geq n-2k-1} \to \{-1, 1\}$ denote the $n$-variable function

\[
G(h, f^1, \ldots, f^r) \overset{\text{def}}{=} \text{sign} \left( b + \sum_{i=1}^{r} \sum_{j=1}^{k-1} (k+1)^{k(i-1)+j} (f^i, \varphi_{\alpha_j}) \right)
\]

(Note that the inner sum starts with $j = 1$ and not 0; this will be important later.) Since each $(f^i, \varphi_{\alpha_j})$ is a $(\pm 1)$-weighted sum of the coordinates of $f^i$, it is clear that $G$ is a halfspace with weight at most $k^{O(n)}$. We will show that any integer-weight halfspace for $G$ over $\{-1, 1\}^n_{\geq n-2k-1}$ must have some weight that is at least $k^{\Omega(n)}$.

To get some more intuition for the function $G$, note that for a block $f^i$ we have that $(f^i, \varphi_{\alpha_j}) = \cdots = (f^i, \varphi_{\alpha_{k-1}}) = 0$ if and only if $f^i$ is one of the two inputs $(1, \ldots, 1)$ or $(-1, \ldots, -1)$ (this is because the constant +1 function and the constant $(-1)$ function are the only two Boolean functions that have all nonconstant Fourier coefficients equal to zero). So, in other words, given an input $f = (b, f^1, \ldots, f^r)$ the value $G(f)$ is obtained as follows: If any block is neither constantly +1 nor constantly
−1, let i be the largest such block, and output the sign of the Fourier coefficient \( \hat{f}(\alpha_j) \), where j is the largest index such that \( \hat{f}(\alpha_j) \) is nonzero. Otherwise output the bit b.

The high-level intuition behind the lower bound is as follows. Consider a single block i and fix all other bits in other blocks \( i' \neq i \) to be 1. By fixing the bit b appropriately, the function G computes exactly H˚astad’s halfspace over the k variables in block i. (We recall that H˚astad’s k-variable halfspace \( F \) over a k-bit input string \( f \in \{-1,1\}^k \) is \( F(f) = \text{sign}(f_f, \varphi_{\alpha}), \) where j is the largest index such that \( f_f, \varphi_{\alpha} \neq 0 \); equivalently, \( F(f) = \text{sign}(\sum_{i=0}^{k-1}(k+1)^i(f, \varphi_{\alpha})) \) gives an explicit representation of the halfspace \( F \).) So applying H˚astad’s weight lower bound for his halfspace \( F \), intuitively the variables in block i should require integer weights growing as \( k^{\Omega(k)} \). Since higher blocks dominate lower blocks in \( G \) and there are \( r = (n - 1)/k \) blocks, intuitively a \( k^{\Omega(k)} \) growth factor within each of \( (n - 1)/k \) blocks means that overall the weights should grow as \( (k^{\Omega(k)})^{(n-1)/k} = k^{\Omega(n)} \).

Unfortunately, this simple reasoning is not quite right when applied to the actual weights \( w_j \) of the input variables \( f'(j) \). This is because in H˚astad’s halfspace all integer coefficients must be large, but they do not actually increase by much; in fact, the integer coefficients of all k variables in H˚astad’s function can be taken to be within a factor of 2 of each other. But, as we shall see, the reasoning of the previous paragraph is essentially correct when a different representation is used, namely, when it is applied to the “Fourier transformed” weights \( \psi_j \) that are the coefficients of \( (f', \varphi_{\alpha}) \) (see (3.5) below), and this suffices to give the desired overall weight bound. We will show that the \( \psi_j \)’s must grow very rapidly, and hence some \( \psi_j \) must be large, and consequently some \( w_j \) must be large.

**The analysis.** Our goal is to prove the following, which immediately gives Theorem 3.1. (Throughout this section \( \beta \) denotes the constant \( \log_2(3/2) \).)

**Theorem 3.2.** If the function G defined in (3.3) satisfies

\[
G(f) = \text{sign} \left( \sum_{i=1}^{r} \sum_{j=0}^{k-1} w_j f'(j) + w_0 b - \theta \right) \quad \forall f \in \{-1,1\}^2 n - 2k - 1;
\]

where each \( w_j \) and \( w_0 \) is an integer, then for some \( j \in \{0, \ldots, k - 1\} \) we have \( w_j \geq (e^{-4k^2 (2(k \log k)/2 - k)(n - 1)/k} / k \).

Following [9], the main step is to prove the following.

**Theorem 3.3.** Suppose that the function G defined in (3.3) satisfies

\[
G(f) = \text{sign} \left( \sum_{i=1}^{r} \sum_{j=0}^{k-1} \psi_j(f', \varphi_{\alpha}) + v_0 b - t \right) \quad \forall f = (b, f_1, \ldots, f_r) \in \{-1,1\}^2 n - 2k - 1;
\]

where each \( \psi_j \) and \( v_0 \) is an integer. Then \( \psi_{k-1} \geq (e^{-4k^2 (2(k \log k)/2 - k)(n - 1)/k} \).

To show that Theorem 3.3 implies Theorem 3.2 we use the following claim, which is a simple consequence of Fourier analysis (see Lemma 2.3 of [9]).

**Claim 1.** For any \( f \in \{-1,1\}^k \) and any \( (w_0, \ldots, w_{k-1}) \in \mathbb{R}^k \), setting

\[
v_a = \frac{1}{k} \sum_{j=0}^{k-1} w_j \varphi_{a,j} \quad \text{for each } a \in \{0, \ldots, k - 1\},
\]

we have that \( \sum_{j=0}^{k-1} w_j f(j) = \sum_{a=0}^{k-1} v_a(f, \varphi_{a,j}) \).
Proof of Theorem 3.2 using Theorem 3.3. Suppose that \( \{w_i^j\}, w_0, \theta \) satisfy (3.4). By Claim 1, for all \( f \in \{-1,1\}^{n-2k-1} \) we have that

\[
G(f) = \text{sign} \left( \sum_{i=1}^{r} \sum_{a=0}^{k-1} v_a^i (f^i, \varphi_{a_i}) + w_0b - \theta \right),
\]

where \( v_a^i = \frac{1}{k} \sum_{j=0}^{k-1} w_j^i \varphi_{a_i}(j) \). We have that \( kv_a^i \) is an integer for all \( i \) and \( a \), and so by Theorem 3.3 we get that \( kv_a^i \geq (e^{-4k^\beta}2^{(k \log k)/2-k})^{(n-1)/k} \), i.e., \( \sum_{j=0}^{k-1} w_j^i \varphi_{a_i}(j) \geq (e^{-4k^\beta}2^{(k \log k)/2-k})^{(n-1)/k} \), which gives Theorem 3.2 since \( |\varphi_{a_i}(j)| = 1 \) for all \( j \). \( \Box \)

3.0.1. Proof of Theorem 3.3. Throughout this section \( \{v_j^i\}, v_0, t \) are as in (3.5). Since all weights are integers we may assume that \( t \) is of the form \( (\text{integer} + \frac{1}{2}) \).

We begin with some straightforward claims that will be useful later.

Claim 2. We have \( v_0 \geq 1 \). Moreover, for each \( i \in [r-1] \) we have \( v_0 \geq \sum_{i' \notin \{i,i+1\}, i' \in [r]} v_0^i - t \).

Proof. First we observe that for \( b \in \{-1,1\} \) we have \( G(b, \varphi_{a_0}, \ldots, \varphi_{a_i}) = b \), which follows from the fact that \( \varphi_{a_i} = 0 \) for all \( i \neq 0 \). By (3.5) this means that we have \( \text{sign}(v_0b + \sum_{i=1}^{r} v_0^i - t) = b \), so it must be the case that \( v_0 > 0 \); since \( v_0 \) is an integer, this means \( v_0 \geq 1 \). Furthermore, taking \( b = -1 \), we find that \( v_0 \geq \sum_{i=1}^{r} v_0^i - t \).

For the second part of the claim, fix any \( i \in [r-1] \) and consider the input \( f = (-1, f^1, \ldots, f^r) \), where \( f^i = \varphi_{a_i} \) for \( i' \notin \{i, i+1\} \) and \( f^{i'} = -\varphi_{a_i} \) for \( i' \in \{i, i+1\} \). This input \( f \) has \( 2k+1 \) bits that are \(-1 \) (this is the only place in the proof where we use an input with this many \(-1 \) bits), and since

\[
G(f) = -1 = \text{sign} \left( -v_0 + \sum_{i' \notin \{i,i+1\}, i' \in [r]} v_0^i - v_0^i - v_0^{i+1} - t \right)
\]

we have that \( v_0 > \sum_{i' \notin \{i,i+1\}, i' \in [r]} v_0^i - v_0^i - v_0^{i+1} - t \). Averaging this with the earlier inequality \( v_0 > \sum_{i=1}^{r} v_0^i - t \) gives the second statement of the claim. \( \Box \)

Claim 3. For every \( i \in [r], j \in [k-1] \) we have \( v_j^i > v_0 \) (in particular, all these weights are positive).

Proof. Fix \( i \in [r], j \in [k-1] \). For \( \varepsilon, b \in \{-1,1\} \) consider the input \( f = (b, f^1, \ldots, f^r) \in \{-1,1\}^n \) defined by \( f^i = \varepsilon \varphi_{a_i} \) and \( f^{i'} = \varphi_{a_i} \) for \( i' \neq i \). Since every \( \varphi_{a_i} \) for \( j \geq 1 \) corresponds to the truth table of a parity function over some nonempty subset of \( \ell \) bits, the string \( f \) has either \( k/2 \) or \( k/2 + 1 \) entries that are \(-1 \) (depending on whether \( b \) is \( +1 \) or \(-1 \)). By the definition of \( G \) we have \( G(f) = \text{sign}(b + (k+1)^{(k-1)\varepsilon}) = \varepsilon \), and, referring to (3.5), we have \( G(f) = \text{sign}(\sum_{i \neq i' \in [r]} v_0^{i'} - t) \). When \( b = \text{sign}(\sum_{i \neq i' \in [r]} v_0^{i'} - t) \) and \( \varepsilon = -b \), this implies that \( v_j^i \geq v_0 + |\sum_{i \neq i' \in [r]} v_0^{i'} - t| \), which implies \( v_j^i \geq v_0 \). \( \Box \)

The proof uses two main lemmas. The first lemma says that weights do not get smaller as we pass from the \( i \)th to the \( (i+1) \)st blocks.

Lemma 3.4. For every \( i \in [r-1] \) and every \( j \in [k-1] \) we have \( v_j^{i+1} \geq v_j^{k-1} \).

Proof. Fix \( i \in [r-1], j \in [k-1] \). Consider the input \( f = (-1, f^1, \ldots, f^r) \in \{-1,1\}^n \) defined by \( f^i = -\varphi_{a_i}, f^{i+1} = \varphi_{a_i}, \) and \( f^{i'} = \varphi_{a_i} \) for \( i' \notin \{i, i+1\} \). This \( f \) has exactly \( k+1 \) entries that are \(-1 \), and the definition of \( G \) implies that \( G(f) = 1 \).
So $G(f) = \sign(v'_{j+1} - v'_{k-1} + \sum_{i' \in (i, i+1), i' \in [r]} v_{i'} - v_0 - t) = 1$, which implies that

$$v'_{j+1} \geq v'_{k-1} - \sum_{i' \in (i, i+1), i' \in [r]} v_{i'} + v_0 + t \geq v'_{k-1},$$

where the final inequality follows from the second statement of Claim 2.

The crucial lemma for us is Lemma 3.6, which says that the $v'_{j}$ weights grow quite significantly (by a factor of $k^{O(k)}$) from the “beginning” to the “end” of each block $i$. Because of the way the function $G$ has been set up, we will be able to show this by a reduction to a weight lower bound that Hästads proves for his halfspace over $k = 2^{\ell}$ variables.

**Definition 3.5.** Let $t_0$ be the index of the first set in the enumeration of subsets of $[\ell]$ such that $\alpha_{t_0}$ has size 2.

**Lemma 3.6.** For every $i \in [\ell]$ we have

$$v'_{i-1} \geq e^{-4k^{2}2^{(k \log k)/2-k}} \cdot v_{t_0}.$$  

**Proof.** Fix any $i \in [\ell]$. Consider the $(k+1)$-variable function defined as

$$(3.6) \quad A(b, f^i) \overset{\text{def}}{=} G(b, \varphi_{a_0}, \ldots, \varphi_{a_0}, f^i, \varphi_{a_0}, \ldots, \varphi_{a_0})$$

$$(3.7) \quad = \sign \left( v_0 b + \sum_{j=0}^{k-1} v_j(f^i, \varphi_{a_j}) + \sum_{i' \neq i' \in [r]} k v_{i'} - t \right),$$

where in line (3.6) $f^i$ appears in the $i$th of the $r$ blocks and all other blocks are set to $\varphi_{a_0}$. Equality (3.7) holds because for each $i' \neq i$, we have that $(\varphi_{a_0}, \varphi_{a_j})$ is 0 for $j \neq 0$ and is $k$ for $j = 0$. For every $(b, f^i) \in \{-1, 1\}^{k+1}$ the corresponding input to $G$ in (3.6) has at most $k+1$ variables set to $-1$, so by the definition of $G$ we have that

$$(3.8) \quad A(b, f^i) = \begin{cases} F_k(f^i) & \text{if } f^i \text{ is neither } \varphi_{a_0} \text{ nor } -\varphi_{a_0}, \\ b & \text{if } f^i \text{ is either } \varphi_{a_0} \text{ or } -\varphi_{a_0}, \end{cases}$$

where $F_k$ is Hästads function on $k$ variables, and $F_k(f^i) = \sign((f^i, \varphi_{a_j}))$, where $j$ is the largest index such that $(f^i, \varphi_{a_j}) \neq 0$. Recall that since $\varphi_{a_0}$ is the constant 1 function, we have $(f^i, \varphi_{a_0}) = \sum_{j=0}^{k-1} f^i(j)$. Thus (3.8) gives us that

$$A \left( \sign \left( \sum_{j=0}^{k-1} f^i(j) \right), f^i \right) = F_k(f^i) \quad \forall f^i \in \{-1, 1\}^k.$$  

Now it is clear that flipping the value of $b$ changes the value of $A(b, f^i)$ only if $f^i$ is either $\varphi_{a_0}$ or $-\varphi_{a_0}$. By (3.7) this implies that for all $f^i \notin \{\varphi_{a_0}, -\varphi_{a_0}\}$ we must have

$$|v_0| < \left| \sum_{j=0}^{k-1} v_j(f^i, \varphi_{a_j}) + \sum_{i' \neq i' \in [r]} k v_{i'} - t \right|.$$  

But this means that the $k$-variable function $A' : \{-1, 1\}^k \rightarrow \{-1, 1\},$

$$(3.9) \quad A'(f^i) \overset{\text{def}}{=} \sign \left( v_0 \left( \sum_{j=0}^{k-1} f^i(j) \right) + \sum_{j=0}^{k-1} v_j(f^i, \varphi_{a_j}) + \sum_{i' \neq i' \in [r]} k v_{i'} - t \right),$$
must equal \( F_k(f^i) \) for all \( f^i \in \{-1, 1\}^k \), because \( \frac{1}{k} \sum_{j=0}^{k-1} f^i(j) \) is always at most 1 in magnitude and equals \( \text{sign}(\sum_{j=0}^{k-1} f^i(j)) \) when \( f^i \) is \( \varphi_{\alpha_0} \) or \( -\varphi_{\alpha_0} \). Scaling the argument to \( \text{sign}(\cdot) \) by a factor of \( k \) in (3.9), we have that

\[
A'(f^i) = \text{sign}\left( v_0 \sum_{j=0}^{k-1} f^i(j) + k \sum_{j=0}^{k-1} v_j^i(f^i, \varphi_{\alpha_j}) + \sum_{i \neq i' \in [r]} kv_j^i - t \right)
\]

is a halfspace over \( \{-1, 1\}^k \) that computes precisely H˚astad’s function \( F_k \). As H˚astad notes (Lemma 2.2 of his paper), we may remove the constant term \( k(\sum_{i \neq i' \in [r]} kv_j^i - t) \) without changing the function. Recalling again that \( (f^i, \varphi_{\alpha_0}) = \sum_{j=0}^{k-1} f^i(j) \), we rewrite the resulting expression for \( A'(f^i) \) as

\[
A'(f^i) = \text{sign}\left( \sum_{j=0}^{k-1} v_j^i(f^i, \varphi_{\alpha_j}) \right),
\]

where \( v_j^i \) equals \( kv_j^i \) for \( j \neq 0 \) and equals \( kv_0^i + v_0 \) for \( j = 0 \). Since these coefficients are all integers, we are in precisely the situation of H˚astad’s Theorem 2.4. The proof of that theorem explicitly establishes (see the second-to-last highlighted equation on p. 489) that \( v_{k-1}^1 \geq e^{-4k^22(k \log k)/2-k} \cdot v_0^1 \), and the lemma is proved. □

Applying Lemmas 3.4 and 3.6 repeatedly and taking \( j \) in Lemma 3.4 to be \( t_0 \) each time, we get that

\[
v_{k-1}^r \geq (e^{-4k^22(k \log k)/2-k}(n-1)/k) v_0^1,
\]

which is at least \( e^{-4k^22(k \log k)/2-k}(n-1)/k \) since \( v_0^1 \) is at least 1 by Claim 3. This proves Theorem 3.3. □

4. Preliminaries on \( \varepsilon \)-approximating halfspaces over Hamming balls.

Let \( f \) be a halfspace over a domain \( S \). We say that \( f \) has an \( \varepsilon \)-approximator of weight \( W \) over \( S \) if there is an integer vector \( (v_1, \ldots, v_n) \in \mathbb{Z}^n \) with max, \( |v_i| \leq W \) and a threshold \( \theta \in \mathbb{R} \) such that

\[
\Pr_{x \in S} [\text{sign}(v \cdot x - \theta) \neq f(x)] \leq \varepsilon,
\]

where the probability is with respect to a uniform choice of \( x \) from \( S \). In the rest of this paper we prove upper and lower bounds on the weight of \( \varepsilon \)-approximators over the Hamming ball \( \{0, 1\}^n \leq k \), where \( k \) is viewed as “small” compared to \( n \).

Related work. In [4] it was shown that for any fixed \( p \in (0, 1) \) and any halfspace \( f \) over \( \{0, 1\}^n \), there is an \( \varepsilon \)-approximating halfspace \( \text{sign}(w \cdot x - \theta) \) of weight \( n2^{O_n(1/\varepsilon^2)} \) for \( f \) with respect to the product distribution \( D_p \), i.e., \( \Pr_{x \sim D_p} [\text{sign}(w \cdot x - \theta) \neq f(x)] \leq \varepsilon \). Here the distribution \( D_p \) is the product distribution over \( \{0, 1\}^n \) such that each coordinate \( x_i \) of a draw from \( D_p \) is independently set to be 1 with probability \( p \). The “\( O_n \)” in the exponent of the weight bound hides a dependence on \( p \).

For constant \( p \in (0, 1/2) \) the distribution \( D_p \) is rather similar to the uniform distribution on \( \{0, 1\}^n \leq pn \) since both distributions are close to being uniform over strings of weight \( pn \). In contrast, we give upper and lower bounds that depend only on \( k \) and \( \varepsilon \), independent of \( n \), but our bounds require that \( k \) be “small” relative to \( n \). Thus the results of [4] may be viewed as addressing the case where \( k \) is “large” (linear in \( n \)), while our results may be viewed as addressing the case where \( k \) is “small.”
Some useful distributions. In proving our upper and lower bounds it will often be simpler for us to work with “nice” distributions which are close to the uniform distribution over \( \{0,1\}^n \leq k \). First we prove some simple observations which we will use in the following sections.

**Observation 2.** Let \( D \) denote the uniform distribution over \( \{0,1\}^n \leq k \) and let \( D_1 \) denote the uniform distribution over \( \{0,1\}^n = k \), the set of all strings with exactly \( k \) ones. The total variation distance \( \|D - D_1\|_1 \) between \( D \) and \( D_1 \) is at most \( 4k/n \).

Moreover, let \( D_2 \) denote the distribution over \( [k]^n \) defined as follows: a draw of \( x \sim D_2 \) is obtained by taking \( x \) to be \( e_{i_1} + e_{i_2} + \cdots + e_{i_k} \), where each of \( i_1, \ldots, i_k \) is drawn independently and uniformly from \([n]\). Then the total variation distance \( \|D - D_2\|_1 \) is at most \( (k^2 + 4k)/n \).

**Proof.** For the first claim, if \( k > n/4 \), then the claimed bound is trivially true, so we assume that \( k < n/4 \). We recall that \( \binom{n}{j}/\binom{n}{m} = j/(n-j+1) \), and that this is at most \( 1/2 \) for \( j \leq n/4 \). So induction gives us that \( \binom{n}{k-2} \leq \frac{3}{4} \binom{n}{k-1} \), \( \binom{n}{k-3} \leq \frac{1}{4} \binom{n}{k-1} \), and so on, so

\[
|\{0,1\}^n \leq k-1| \leq \sum_{j=0}^{k-1} \frac{1}{2^j} \times |\{0,1\}^{n} = k-1| \leq 2|\{0,1\}^{n} = k-1|,
\]

and hence

\[
\frac{|\{0,1\}^n \leq k-1|}{|\{0,1\}^n \leq k|} \leq \frac{2|\{0,1\}^{n-k}\leq 1|}{|\{0,1\}^{n} \leq k|} \leq 2 \frac{2}{|\{0,1\}^{n-k}\leq 1|} \leq 4k/n.
\]

So, the total variation distance between \( D \) and \( D_1 \) is

\[
\sum_{x:D(x) \geq D_1(x)} (D(x) - D_1(x)) = \frac{|\{0,1\}^n \leq k| - |\{0,1\}^n \leq k|}{|\{0,1\}^n \leq k|} \leq 4k/n.
\]

For the second claim, let \( \text{dup} \) be the event that \( x_i > 1 \) for some \( i \). We have

\[
D_2(\text{dup}) = \sum_{i=1}^{k-1} \frac{i}{n} \leq \frac{k(k-1)}{2n}.
\]

Conditioned on the event \( \neg \text{dup} \), the distribution \( D_2 \) is identical to \( D_1 \). Thus for any event \( E \) we have

\[
|D_1(E) - D_2(E)| = |D_1(E) - D_2(E) | \neg \text{dup} D_2(\neg \text{dup}) - D_2(E) | \text{dup} D_2(\text{dup})| \\
\leq |D_1(E) - D_2(E) | \neg \text{dup} D_2(\neg \text{dup}) + D_2(\text{dup})| \\
= |D_1(E) - D_1(E) D_2(\neg \text{dup})| + D_2(\text{dup})| \\
= D_1(E) \cdot (1 - D_2(\neg \text{dup})) + D_2(\text{dup})| \\
\leq 1 - D_2(\neg \text{dup}) + D_2(\text{dup}) = 2D_2(\text{dup}) \leq \frac{k(k-1)}{n}
\]

by (4.2). So \( \|D_2 - D_1\|_1 \leq \frac{k(k-1)}{n} \), which together with the first claim and the triangle inequality for variation distance gives the desired bound. \( \square \)

We close this section with the following notation, which will be useful later. Let \( Z_{n,k} \) denote the set

\[
Z_{n,k} = \{ x = (x_1, \ldots, x_n) \in \mathbb{Z}^n : x_i \geq 0 \ \forall i \text{ and } x_1 + \cdots + x_n = k \}.
\]

Let \( \Phi : [n]^k \rightarrow Z_{n,k} \) denote the mapping \( \Phi(a) = \sum_{i=1}^{k} e_{a_i} \). Thus a draw of \( x \sim D_2 \) is obtained by drawing \( a \) uniformly from \([n]^k\) and setting \( x = \Phi(a) \).
5. Upper bound for approximating halfspaces. In this section we prove our main positive result on approximating halfspaces over \( \{0,1\}^n_k \) using small weights, which is the following.

**Theorem 5.1.** Let \( f \) be any halfspace over \( \{0,1\}^n_k \). Let \( \varepsilon, k \) satisfy \( \varepsilon k^2 \leq c \), where \( c > 0 \) is a (small) universal constant. Then there is an \( \varepsilon \)-approximator for \( f \) over \( \{0,1\}^n_k \) that has weight \( k^{O(k/\varepsilon)} \).

As noted in the introduction, it is easy to see that there are halfspaces over the entire Boolean cube \( \{0,1\}^n \) that require weight \( \Omega(\sqrt{n}) \) for \( \varepsilon \)-approximation even when \( \varepsilon \) is (say) 1/5; an example of such a halfspace is \( \text{sign}(x_1 + x_2 + \cdots + x_{n-1} + nx_n) \) (see [22] for the proof). In contrast, Theorem 5.1 shows that over Hamming balls of any constant radius, every halfspace can be approximated to any constant accuracy using weights that are independent of \( n \).

Here is some intuition before the formal proof. The proof works by showing that every halfspace can be \( \varepsilon/2 \)-approximated with respect to the distribution \( D_2 \) (this is sufficient to establish the theorem by Observation 2). To \( \varepsilon/2 \)-approximate an arbitrary halfspace \( f \) with respect to \( D_2 \), the argument proceeds as follows. After sorting the weights, we first define a collection of \( t = O(k/\varepsilon) \) “key coordinates” in \( \{1, \ldots, n\} \) (these are just \( t \) coordinates which are evenly spaced out in \( \{1, \ldots, n\} \)). Then we define a set \( S \subset Z_n, k \) of “key inputs,” which are the elements of \( Z_n, k \) that have nonzero entries only in the key coordinates. Using a linear programming argument, we show that there is a halfspace \( h' \) that depends only on the \( t \) key coordinates, has weight \( k^{O(k)} \), and agrees with \( f \) on all key inputs. An additional crucial property of \( h' \) is that its weights are sorted in the same order as the weights of \( f \). We then define an \( n \)-variable halfspace \( h \) by basing the weights of the other \( n - t \) nonkey coordinates in a natural way on the weights that \( h \) assigns to the key coordinates. We use the sortedness of the weights of \( h' \) to characterize the error points of \( h \). Finally, we upper bound the error of \( h \) by using this characterization together with a simple upper bound on the edge boundary of monotone Boolean-valued functions over the domain \([t]^k\).

**Proof of Theorem 5.1.** We first note that if \( k \in \{0,1\} \), then there is a weight-1 exact representation of \( f \), so we henceforth assume that \( k \geq 2 \).

Let \( w_1,\ldots,w_\ell, \theta' \) be a weight representation of \( f \) over \( \{0,1\}^n_k \), so \( f(x) = \text{sign}(w \cdot x - \theta) \) for all \( x \in \{0,1\}^n_k \). We may assume that each \( w_i \) is an integer and that \( \theta' \) is of the form \( (1/2) + \frac{1}{\ell} \). Additionally, we may assume that the weights are sorted \( w_1 \leq \cdots \leq w_\ell \), since if this is not the case, we can rename variables to make this condition hold. We use the representation \( w, \theta' \) to extend the domain of \( f \) to all of \( \mathbb{R}^n \); i.e., we define \( f(x) = \text{sign}(w \cdot x - \theta') \) for all \( x \in \mathbb{R}^n \).

**Key coordinates and key inputs.** Let \( t = O(k/\varepsilon) \). Note that if \( t \geq n \), then by Theorem 2.1 there is indeed an exact representation for \( f \) over \( \{0,1\}^n_k \) that has weight \( k^{O(k)} \); thus we may assume that \( t < n \). In fact, by the assumptions on \( \varepsilon, k \), and \( n \) in the statement of the theorem we may assume that \( k \leq n/t \); this will be useful later.

We define the set \( KC \subset [n], |KC| = t \) of “key coordinates” to be a fixed set \( KC = \{\text{key}_1 = 1, \text{key}_2, \ldots, \text{key}_t = n\} \) of values in \([n]\) that are equally spaced as much as possible, i.e., for all \( j, j' \in [t-1] \) we have \( \text{key}_{j+1} - \text{key}_j = \text{key}_{j'+1} - \text{key}_{j'} \pm 1 \).

We next define the set \( KI \subset Z_n, k \) of “key inputs” as \( KI = \{x \in Z_n, k : \forall i, \text{ if } x_i > 0, \text{ then } i \in KC\} \),
so \( x \in Z_{n,k} \) is a key input if and only if all of its nonzero coordinates are key coordinates.

**A low-weight halfspace \( h \) that agrees with \( f \) on all key inputs.** Our next step is to establish the existence of a low-weight halfspace that depends only on the key coordinates and agrees with \( f \) on all key inputs. This is done via a linear programming argument quite similar to the proof of Theorem 2.1.

**Lemma 5.2.** There is a halfspace \( h'(x) = \text{sign}(v' \cdot x - \theta) \) with the following properties:

1. For each \( i \notin \text{KC} \) we have \( v'_i = 0 \) (so \( h \) depends only on the key coordinates).
2. For each \( i \in \text{KC} \) we have that \( v'_i \) is an integer satisfying \( |v'_i| \leq k^{O(i)} \).
3. For each \( j \in [t-1] \) we have \( v'_{\text{key}_j} \leq v'_{\text{key}_{j+1}} \).
4. \( h'(x) = f(x) \) for every key input \( x \in \text{KI} \).

**Proof.** We obtained the desired integer weights \( (v'_i)_{i \in \text{KC}} \) and the threshold \( \theta \) as the solution to a linear program, which we now describe. Each key input \( x \in \text{KI} \) defines a linear constraint over the \( t+1 \) variables \( (v'_i)_{i \in \text{KC}}, \theta \) in the following way:

\[
f(x) \cdot \left( \sum_{i \in \text{KC}} v'_i x_i - \theta \right) \geq 1.
\]

The linear program additionally contains \( t-1 \) constraints of the form

\[
v'_{\text{key}_j} \leq v'_{\text{key}_{j+1}} \quad \forall j \in [t-1].
\]

This is a feasible linear program, since taking \( v'_i = 2w_i \) for all \( i \in \text{KC} \), \( v'_i = 0 \) for all \( i \notin \text{KC} \), and \( \theta = 2\theta' \) is a feasible solution. (To see that this works, observe that for any \( x \in \text{KI} \) the total value of \( w \cdot x \) is entirely contributed by coordinates in \( \text{KC} \).) It is clear that any feasible solution satisfies items (1), (3), and (4) of the lemma, so it remains only to show that there is a feasible solution satisfying the weight bound (2). This follows from the same arguments used in the proof of Theorem 2.1 with trivial modifications (the fact that there are now \( t+1 \) unknowns in the linear program leads to the claimed bound of \( k^{O(t)} \) rather than \( k^{O(n)} \), as was the case in Theorem 2.1). \( \square \)

**Filling in the other weights.** We now define the halfspace \( h \) that has weights for all coordinates (not just the key coordinates). The halfspace \( h \) is defined as \( h(x) = \text{sign}(v \cdot x - \theta) \) in a very natural way as follows: For each key coordinate \( i \in \text{KC} \) we take \( v_i = v'_i \). For each nonkey coordinate \( i \notin \text{KC} \), let \( j \) be such that \( \text{key}_{j-1} < i < \text{key}_j \), i.e., \( \text{key}_j \) is the first key coordinate immediately after \( i \); we take \( v_i = v'_{\text{key}_j} \). For example, if \( v' = (3, 0, 0, 4, 0, 6) \), then \( v = (3, 4, 4, 4, 6, 6) \). Note that the weights \( v_i \) satisfy \( v_1 \leq v_2 \leq \cdots \leq v_n \); this will be useful later.

We will show that this halfspace \( h(x) \) is the \( \varepsilon \)-approximator for \( f \) claimed in the theorem statement. It is clear that the weight of \( h \) is at most \( k^{O(t)} = k^{O(k/\varepsilon)} \), as desired; it remains to show that \( \Pr_{x \sim \text{D}_2} [h(x) \neq f(x)] \leq \varepsilon/2 \), or, equivalently, that at most an \( \varepsilon/2 \) fraction of points \( a \in \{n\}^n \) have \( h(\Phi(a)) \neq f(\Phi(a)) \).

**Bounding \( \Pr_{a \in \{n\}^n} [h(\Phi(a)) \neq f(\Phi(a))] \).** We define a function \( \text{up} : [n-1] \rightarrow \text{KC} \) as follows: \( \text{up}(i) = \text{key}_j \), where \( \text{key}_j \) is the smallest element of \( \text{KC} \) satisfying \( i < \text{key}_j \). Similarly we define \( \text{down} : [n-1] \rightarrow \text{KC} \) as \( \text{down}(i) = \text{key}_j \), where \( \text{key}_j \) is the largest element of \( \text{KC} \) satisfying \( \text{key}_j \leq i \). Each \( i \in [n-1] \) has \( \text{up}(i) = \text{down}(i) + 1 \).
For an arbitrary \(a \in [n-1]^k\) we define the “upper key neighbor” of \(a\) and “downward key neighbor” of \(a\) as

\[
\text{ukn}(a) = (\text{up}(a_1), \ldots, \text{up}(a_k)) \in (KC)^k, \\
\text{dkn}(a) = (\text{down}(a_1), \ldots, \text{down}(a_k)) \in (KC)^k,
\]

respectively. It is easy to see that for each \(a \in [n-1]^k\), both \(\Phi(\text{ukn}(a))\) and \(\Phi(\text{dkn}(a))\) are key inputs. Thus Lemma 5.2 ensures that \(\text{sign}(v \cdot \Phi(v) - \theta) = \text{sign}(w \cdot \Phi(w - \theta))\) for all \(a \in [n-1]^k\), and likewise for \(\Phi(\text{dkn}(a))\).

We next observe that by the monotonicity of the weights \(v, \ldots, v_n\), we have that every \(a \in [n-1]^k\) satisfies

\[
v \cdot \Phi(\text{dkn}(a)) \leq v \cdot \Phi(a) \leq v \cdot \Phi(\text{ukn}(a)).
\]

Consequently if \(a \in [n-1]^k\) is such that \(\text{sign}(v \cdot \Phi(\text{dkn}(a)) - \theta) = \text{sign}(v \cdot \Phi(\text{ukn}(a)) - \theta)\), then \(\text{sign}(v \cdot \Phi(a) - \theta)\) must equal the same value, and hence for such an \(a\) we have

\[
\text{sign}(w \cdot \Phi(\text{dkn}(a)) - \theta') = \text{sign}(v \cdot \Phi(\text{dkn}(a)) - \theta) = \text{sign}(v \cdot \Phi(a) - \theta) = \text{sign}(w \cdot \Phi(\text{ukn}(a)) - \theta') \tag{5.1}
\]

By monotonicity of the weights \(w_1, \ldots, w_n\) we have that \(w \cdot \Phi(\text{dkn}(a)) \leq w \cdot \Phi(a) \leq w \cdot \Phi(\text{ukn}(a))\), so, if (5.1) holds, all the quantities in (5.1) above are also equal to \(\text{sign}(w \cdot \Phi(a) - \theta')\). Thus we have shown that if \(a \in [n-1]^k\) is such that \(\text{sign}(v \cdot \Phi(\text{dkn}(a)) - \theta) = \text{sign}(v \cdot \Phi(\text{ukn}(a)) - \theta)\), then \(\text{sign}(v \cdot \Phi(a) - \theta) = \text{sign}(w \cdot \Phi(a) - \theta')\), i.e., \(h(\Phi(a)) = f(\Phi(a))\). We observe that at most a \(k/n\) fraction of all inputs \(a \in [n]^k\) have \(a_j = n\) for any \(j\); by the conditions on \(k, \varepsilon, n\) in the statement of the theorem, \(k/n\) may be assumed to be at most \(\varepsilon/4\). So to finish the proof of the theorem, it suffices to show the following, which we refer to as statement (*):

(*) At most an \(\varepsilon/4\) fraction of all points \(a \in [n-1]^k\) have \(\text{sign}(v \cdot \Phi(\text{dkn}(a)) - \theta) = -1\) and \(\text{sign}(v \cdot \Phi(\text{ukn}(a)) - \theta) = 1\).

We first note that for any two elements \(i, j \in [t-1]\) we have

\[
|\text{down}^{-1}(\text{key}_i)|, |\text{down}^{-1}(\text{key}_j)| \in \{[n/t], [n/t] + 1\},
\]

and we recall from the bounds on \(t\) stated at the beginning of the proof that consequently \(|\text{down}^{-1}(i)|, |\text{down}^{-1}(j)| \geq k\). As a result, for any two vectors \((i_1, \ldots, i_k) \in [t-1]^k\) and \((j_1, \ldots, j_k) \in [t-1]^k\), we have that the two sets

\[
\{a \in [n-1]^k : \text{down}(a_\ell) = i_\ell\text{ for all } \ell = 1, \ldots, k\} \quad \text{and} \quad \{b \in [n-1]^k : \text{down}(b_\ell) = j_\ell\text{ for all } \ell = 1, \ldots, k\}
\]

have sizes that differ by at most a multiplicative factor of \((1 + \frac{1}{2})^k < 3\). Hence to establish (*) it suffices to show that at most a \(\varepsilon/12\) fraction of all vectors \((i_1, \ldots, i_k) \in [t-1]^k\) have

\[
\text{sign}(v \cdot \Phi(\text{key}_{i_1}, \ldots, \text{key}_{i_k}) - \theta) = -1 \quad \text{and} \quad \text{sign}(v \cdot \Phi(\text{key}_{i_1+1}, \ldots, \text{key}_{i_k+1}) - \theta) = 1.
\]

We define a Boolean-valued function \(F : [t-1]^k \rightarrow \{-1, 1\}\) as follows:

\[
F(i_1, \ldots, i_k) = \text{sign} (v \cdot \Phi(\text{key}_{i_1}, \ldots, \text{key}_{i_k}) - \theta).
\]

The monotonicity of the weights \(v_{\text{key}_{i_1}}, \ldots, v_{\text{key}_{i_k}}\) implies that \(F\) is a monotone non-decreasing function over \([t-1]^k\): if \(r, s \in [t-1]^k\) satisfy \(r_i \leq s_i\) for all \(i \in [k]\), then it
cannot be the case that $F(r) = 1$ and $F(s) = -1$. Now we upper bound the desired probability using a union bound:

$$
\Pr_{(i_1, \ldots, i_k) \in [t-1]^k} [F(i_1, \ldots, i_k) \neq F(i_1 + 1, \ldots, i_k + 1)] \\
\leq \Pr_{(i_1, \ldots, i_k) \in [t-1]^k} [F(i_1, \ldots, i_k) \neq F(i_1 + 1, i_2, \ldots, i_k)] \\
+ \Pr_{(i_1, \ldots, i_k) \in [t-1]^k} [F(i_1 + 1, i_2, \ldots, i_k) \neq F(i_1 + 1, i_2 + 1, i_3, \ldots, i_k)] + \cdots \\
+ \Pr_{(i_1, \ldots, i_k) \in [t-1]^k} [F(i_1 + 1, \ldots, i_k - 1 + 1, i_k) \neq F(i_1 + 1, \ldots, i_k + 1)].
$$

By the monotonicity of $F$, each of the $k$ probabilities on the right-hand side (RHS) is at most $1/(t - 1)$ (since fixing all the values of the other $k - 1$ coordinates, there can be at most one setting of the remaining free coordinate which causes the value of $F$ to change). For a suitable choice of the hidden constant in $t = O(k/\varepsilon)$, we have that $1/(t - 1) \leq \varepsilon/(12k)$. Thus the RHS above is at most $\varepsilon/12$ as desired. This concludes the proof of Theorem 5.1.  

6. Lower bounds for approximating halfspaces. Recall that the $n$-variable halfspace $DL$ is defined as $DL(x) = \text{sign}(\sum_{i=1}^{n} (-2)^{i}x_i + 1)$. Our main result in this section is a lower bound on the weight of any $\varepsilon$-approximator for $DL$.

**Theorem 6.1.** For sufficiently large $n$, $k \geq 3$ and $\frac{1}{2} \cdot \left(\frac{1}{4\kappa} \right)^k > \varepsilon \geq 4k/n$, any $\varepsilon$-approximator for $DL$ over $\{0, 1\}^n_{\leq k}$ must have weight at least $k^{\Theta(1)/\varepsilon^{1/(k - 1)} - 1}$.

**Discussion.** It is easy to see that for all $\varepsilon$, the function $DL$ has an $\varepsilon$-approximator over $\{0, 1\}^n$ of weight $O(1/\varepsilon)$. So Theorem 6.1 shows that for a specific natural function, taking $k$ to be constant and letting $\varepsilon$ vary, getting an $\varepsilon$-approximator over the Hamming ball $\{0, 1\}^n_{\leq k}$ (for $k$ constant) requires weights that are exponentially larger than the weights required for $\varepsilon$-approximation over the entire Boolean cube. Theorem 6.1 is also in sharp contrast with the recent upper bound of [3], which shows that any Boolean halfspace has an $\varepsilon$-approximator over the entire Boolean cube which has weight at most quasipoly$(1/\varepsilon)$ (as a function of $\varepsilon$).

**6.1. Proof sketch of Theorem 6.1.** Since the proof of Theorem 6.1 is somewhat involved we give an outline here. At a very high level, the idea is that in order for a linear threshold function $\text{sign}(v \cdot x - \theta)$ to be a good approximator for $DL$, it should be the case that (roughly speaking) $v_i > 0$ for even $i$, $v_i < 0$ for odd $i$, and the magnitudes of the weights $|v_i|$ increase sharply with $i$; the essence of the proof is to show that if any of these conditions are “badly violated,” then $\text{sign}(v \cdot x - \theta)$ must disagree with $DL$ on many inputs.

In more detail, let $\text{sign}(v \cdot x - \theta)$ be an arbitrary integer weight halfspace which is a $2\varepsilon$-approximator for $DL$ with respect to $D_1$ (by Observation 1 it suffices to consider such approximators). We first show (Claim 4) that without loss of generality we may assume that the threshold $\theta$ is 0 and the weights $v_i$ are positive for even $i$ and negative for odd $i$. This is not too difficult; the bulk of our work is to show that overall the magnitudes of the weights must increase significantly from smallest to largest, and thus the largest magnitude weight must be very large (since the smallest magnitude weight has magnitude at least 1). To do this, we consider the weights in order of increasing magnitude and consider disjoint “blocks” of the smallest-magnitude weights, the next-smallest-magnitude weights, and so on. We show (Lemma 6.2) that either there are large weights, or else almost all of the blocks are “pure,” meaning
that they either consist almost entirely of positive (even-index) weights, or consist almost entirely of negative (odd-index) weights. Finally, the argument concludes by showing that if almost all of the blocks are “pure” as described above, then in fact the halfspace must err on a significant fraction of all inputs.

6.2. Proof of Theorem 6.1. Let \( \varepsilon \geq 4k/n \), and assume that \( \text{sign}(v \cdot x - \theta) \) is an integer-weight halfspace which is a \( 2\varepsilon \)-approximater for \( DL \) with respect to \( D_1 \). (Recall that \( D_1 \) is the uniform distribution over \( \{0, 1\}^n_k \) \( \) We will show that if no \( |v_i| \) exceeds \( k^{\Theta(1)/\varepsilon^{1/(k-1)}-1} \), then \( \text{sign}(v \cdot x - \theta) \) cannot be a \( 2\varepsilon \)-approximater for \( DL \).

We first observe that the upper bound on \( \varepsilon \) in the theorem statement gives us \( \varepsilon \leq 1000^{-k} \), and that by combining the upper and lower bounds on \( \varepsilon \) we may assume \( k \leq O(\frac{\log n}{\log \log n}) \); these bounds will be useful later.

Claim 4. We may assume without loss of generality that all of the following conditions hold:

1. \( \theta = 0 \);
2. each coordinate \( v_i \) is a nonzero integer;
3. \( v_i > 0 \) for \( i \) even and \( v_i < 0 \) for \( i \) odd.

Proof. We first show how to obtain conditions (1) and (2) at the cost of only a multiplicative-factor increase of \( \Theta(k) \) in the weights (this factor of \( \Theta(k) \) corresponds to the “-1” at the end of the exponent of the weight bound of Theorem 6.1). Then we show how to further obtain condition (3) at the cost only of decreasing \( n \) from its original value down to some \( n' \in [n/2, n] \) and of increasing \( \varepsilon \) from its original value by at most a factor of 2.

As noted in the preliminaries we may assume that \( \theta \) is of the form (integer + \( \frac{1}{2} \)). Let \( u \in \mathbb{R}^n \) denote the vector \( u = (1, \ldots, 1) \). It is easy to verify that the halfspace \( \text{sign}((2kv - 2\theta u) \cdot x) \) agrees with \( \text{sign}(v \cdot x - \theta) \) on every \( x \in \{0, 1\}^n_k \), because for \( x \in \{0, 1\}^n_k \) we have

\[
(2kv - 2\theta u) \cdot x = 2kv \cdot x - 2k\theta = 2k(v \cdot x - \theta).
\]

Next, we observe that since \( 2kv_i \) is even and \( 2\theta \) is odd, we have that each coordinate of \( (2kv - 2\theta u) \) is a nonzero integer. Thus we have achieved conditions (1) and (2) at the cost of at most a \( \Theta(k) \) multiplicative factor for the largest weight.

So, let us suppose that \( \text{sign}(v \cdot x) \) achieves conditions (1) and (2); we now deal with the signs of the weights. Let \( P \subseteq [n] \) be the set of positive weights, \( P \overset{\text{def}}{=} \{ i : v_i > 0 \} \), and let \( N \overset{\text{def}}{=} [n] \setminus P \) be the set of negative weights, \( N = \{ i : v_i < 0 \} \). Let \( E \subset [n] \) denote the set \( \{2, 4, \ldots, 2[n/2]\} \) of even indices, and let \( O = [n] \setminus E \) denote the set of odd indices in \( [n] \).

We claim that we have \( |N \cap E| \leq \frac{n}{300k} \) and \( |P \cap O| \leq \frac{n}{300k} \). To see why this must be true, suppose \( |N \cap E| > \frac{n}{300k} \). Then there are at least \( \binom{|N \cap E|}{k} \geq \binom{n}{k} \) inputs \( x \in \{0, 1\}^n_k \) of the form \( x = e_i + \cdots + e_i \), where \( i_1, \ldots, i_k \) are distinct and all belong to \( N \cap E \). For each such \( x \) we have \( v \cdot x < 0 \) (because all the weights which contribute to \( v \cdot x \) are negative) but \( DL(x) = 1 \) (because all the bits that are set to 1 in \( x \) are in even coordinates), and hence \( \text{sign}(v \cdot x) \) is in error on each such \( x \). This means that \( \text{sign}(v \cdot x) \) has an error rate at least

\[
\binom{n}{k} \frac{n}{300k} \geq \left( \frac{n}{200k} - (k - 1) \right)^k \geq \left( \frac{1}{200k} - \frac{k - 1}{n} \right)^k > \left( \frac{1}{400k} \right)^k,
\]

where the second (strict) inequality holds for sufficiently large \( n \) because \( k = o(\log n) \) as noted above. From our bounds on \( \varepsilon \) and \( k \) the quantity (6.1) is greater than \( 2\varepsilon \); but
this contradicts the assumption that \( \text{sign}(v \cdot x) \) is a \( 2\varepsilon \)-approximator of \( f \) over \( \{0, 1\}^{n_k}_k \). Thus it must indeed be the case that \( |N \cap E| \leq \frac{n}{200k} \). The same argument works for \( P \cap O \). Thus, we have established that indeed \( |N \cap E| \leq \frac{n}{200k} \) and \( |P \cap O| \leq \frac{n}{200k} \).

So an overwhelming majority of the even \( i \) lie in \( P \), and an overwhelming majority of the odd \( i \) lie in \( N \). Let \( G' \) be defined as \( G' = (P \cap E) \cup (N \cap O) \); intuitively, \( G' \) is the set of \( \text{“good”} \) indices \( i \) for which \( v_i \) has the \( \text{“right”} \) sign. The preceding paragraph gives us that \( |G'| \geq (1 - \frac{1}{1000})n \).

Viewing the elements of \( G' \) as being sorted in increasing order, it may be the case that \( G' \) contains multiple consecutive even elements or multiple consecutive odd elements, i.e., we could have \( G' = \{1, 3, 5, 7, 8, 10, 11, 14, \ldots \} \) and the first 4 points in \( G' \) would all belong to \( O \). Let \( G \) be the subset of \( G' \) obtained by going through the points of \( G' \) from smallest to largest and greedily keeping the first (odd, even, odd, even, \ldots) points of alternating parity that we encounter (so if \( G' \) were as in the above example, we would have \( G' = \{1, 8, 11, 14, \ldots \} \)). For a point \( i \) (like 3 in the above example) to be discarded from \( G' \), it must be the case that \( i - 1 \) does not belong to \( G' \). Since at most \( \frac{50}{100} \) points do not belong to \( G' \), we have that the number of points in \( G' \) that are discarded in constructing \( G \) from \( G' \) is at most \( \frac{n}{100} \). Thus overall we have that \( |G| \geq (1 - \frac{1}{1000})n \). Consequently, of the \( \binom{n}{k} \) points in \( \{0, 1\}^{n_k}_k \), at least

\[
\binom{|G|}{k} \geq \left( \frac{1 - \frac{1}{50k}}{k} \right)^n \geq \left( \frac{1 - \frac{1}{50k}}{k} \right)^n \geq \frac{1}{2}.
\]

this is at least half of the points in \( \{0, 1\}^{n_k}_k \). Let us restrict the halfspace \( \text{sign}(v \cdot x) \) to the domain \( \{0, 1\}^{n_k}_G \). Even if all the error points of \( \text{sign}(v \cdot x) \) were to lie in \( \{0, 1\}^{n_k}_G \), since \( \text{sign}(v \cdot x) \) has error rate at most \( 2\varepsilon \) over \( \{0, 1\}^{n_k}_k \), it must have error rate at most \( 4\varepsilon \) over \( \{0, 1\}^{n_k}_G \). Moreover, since the points in \( G \) (going from smallest to largest) alternate parity (odd, even, odd, even, \ldots) we have that \( DL \) over the domain \( \{0, 1\}^{n_k}_G \) is completely isomorphic to \( DL \) over the domain \( \{0, 1\}^{n_k}_G \). Thus it suffices to analyze the halfspace \( \text{sign}(v \cdot x) \) over the domain \( \{0, 1\}^{n_k}_G \). As claimed in the first paragraph of the proof, the number of variables has gone down by at most a factor of 2 (from \( n \) to \( |G| \)) and the error bound has at most doubled from \( 2\varepsilon \) to \( 4\varepsilon \), so the claim is proved.

Using the above claim, for the rest of the proof we assume that the halfspace \( \text{sign}(v \cdot x) \) satisfies conditions (1)–(3). Next, as described in the overview at the start of this subsection, we divide the weights into disjoint blocks according to their magnitudes and show that almost all the blocks are \( \text{“pure”} \) (composed almost entirely of even-indexed weights, or almost entirely of odd-indexed weights).

Fix \( \pi : [n] \to [n] \) to be a permutation which sorts the weights \( v_1, \ldots, v_n \) in increasing order of magnitude, i.e., \( 0 < |v_{\pi(1)}| \leq |v_{\pi(2)}| \leq \cdots \leq |v_{\pi(n)}| \). (If the weights \( v_i \) have all distinct magnitudes, then there is a unique such permutation \( \pi \), and otherwise we fix any such \( \pi \).) Let \( b \triangleq \Theta(1)/\varepsilon^{1/(k-1)} \). If any weight has
\[ |v_i| > (k/2)^{b/1000}, \text{ then we are done, so we assume that each } i \text{ has } |v_i| \leq (k/2)^{b/1000}. \]

We partition \([n]\) into \(b\) blocks \(S_1, \ldots, S_b\) whose sizes are as nearly even as possible, i.e.,

\[ S_1 = \{ \pi(1), \ldots, \pi(|S_1|) \}, \ldots, S_b = \{ \pi(n - |S_b| + 1), \ldots, \pi(n) \}, \]

where there is a fixed value \(s \approx n/b\) such that \(|S_i| \in \{ s, s + 1 \}\) for all \(1 \leq i \leq b\). Note that \(S_1\) consists of the smallest-magnitude weights, \(S_2\) consists of the next-smallest-magnitude weights, and so on.

We say that a block \(S_i\) is pure if at least \(\frac{999}{1000}\) of the coefficients \((v_j)_{j \in S_i}\) have the same sign; equivalently, \(S_i\) is pure if at least this fraction of the elements of \(S_i\) have the same parity (almost all are even, or almost all are odd). We say that a pure block is “pure odd” (“pure even”) if \(\frac{999}{1000}\) of its elements are odd (even). A block which is not pure is said to be impure.

We have the following lemma.

**Lemma 6.2.** At least \(\frac{999}{1000}\) blocks are pure.

**Proof.** We introduce a different notion, that of a block being “narrow,” and use this notion to prove the lemma. We show that at least \(\frac{999}{1000}\) of all blocks are narrow, and that at most \(\frac{1}{1000}\) of all blocks are both narrow and impure; this gives the lemma.

For a block \(S_j\) let \(R_j \geq 1\) denote the ratio \((\text{largest magnitude of any weight in the block})/(\text{smallest magnitude of any weight in the block})\), i.e., \(R_j = |v_{\pi(i_1)}|/|v_{\pi(i_2)}|\), where \(\pi(i_1), \pi(i_2) \in S_j\) and \(|v_{\pi(i_1)}| \leq |v_{\pi(i')}| \leq |v_{\pi(i_2)}|\) for all \(\pi(i') \in S_j\). (Note that this ratio is well defined for all \(j = 1, \ldots, b\) because each weight \(v_i\) is nonzero.) We say that a block \(S_j\) is narrow if \(R_j \leq k/2\).

We first show that at least \(\frac{999}{1000}\) blocks are narrow. Recall that \(|v_{\pi(n)}| \leq (k/2)^{b/1000}\). Since \(|v_{\pi(n)}| \geq |v_{\pi(n)}|/|v_{\pi(1)}| \geq \prod_{i=1}^b R_i\) it must be the case that at least \(\frac{999}{1000}\) blocks are narrow, since otherwise we would have \(\prod_{i=1}^b R_i > (k/2)^{b/1000}\).

We next claim that if more than \(b/1000\) blocks \(S_i\) are both narrow and impure, then we have \(\Pr_{x \in \{0,1\}^n} [\text{sign}(v \cdot x) \neq \text{DL}(x)] > 2\varepsilon\). To see this, fix any block \(\ell\) that is both narrow and impure. Consider an input \(x = \sum_{j=1}^k c_{i_j}\) chosen uniformly from \(\{0,1\}^k\) conditioned on \(i_1, \ldots, i_k\) all belonging to \(S_\ell\). Some sign—either positive or negative—must constitute the majority of the largest \(\frac{1}{2000}\) elements of \(\{v_j\}_{j \in S_\ell}\); say that sign is positive. With probability at least \(\frac{1}{2000}\) the element \(v_{i_k}\) will belong to this positive subset of the \(\frac{1}{2000}\) largest elements of \(\{v_j\}_{j \in S_\ell}\). On the other hand, the smallest \(1 - \frac{1}{2000}\) of the elements of \(\{v_j\}_{j \in S_\ell}\) must also contain at least \(\frac{1}{2000} \cdot |S_\ell|\) negative elements (because \(S_\ell\) is impure), and with probability \(\frac{1}{2000}\) the elements \(v_{i_1}, \ldots, v_{i_{k-1}}\) will all belong to this set of negative elements. Thus, under the conditioning on \(x\) described above, with probability at least \(1/2^{O(k)}\) we have that

\[(6.2) \quad (-1)^{i_1} = \cdots = (-1)^{i_{k-1}} \neq (-1)^{i_k},\]

i.e., \(i_1, \ldots, i_{k-1}\) all have the same parity (odd or even) but \(i_k\) has the opposite parity (even or odd, respectively). However, since \(S_\ell\) is narrow, the magnitude of \(v_{i_k}\) can be at most \(k/2\) times the minimum magnitude of any of \(v_{i_1}, \ldots, v_{i_{k-1}}\). Since \(k \geq 3\), it follows that we have that \(\text{sign}(v \cdot x) = (-1)^{i_1}\); but this is incorrect since \(\text{DL}(x) = (-1)^i\) (because \(i_k\) is the largest value in \(i_1, \ldots, i_k\)). Thus, conditioned on \(i_1, \ldots, i_k\) all belonging to \(S_\ell\), we have that \(x\) is classified incorrectly by \(\text{sign}(v \cdot x)\) with probability at least \(1/2^{O(k)}\). The probability (over a random \(x \in \{0,1\}^n\)) that all \(k\) coordinates of \(x\) belong to \(S_\ell\) is easily seen to be at least \(1/(2b)^k\). Assuming that at least \(b/1000\) blocks
are both narrow and impure, we get that overall the error rate $\Pr_{x \in \{0,1\}^n} \left[ \text{sign}(v \cdot x) \neq DL(x) \right]$ is at least

\[
\frac{b}{1000} \cdot \frac{1}{2^k} \cdot \frac{1}{2^{O(k)}},
\]

which exceeds $2\varepsilon$ by our choice of $b$.

From the above paragraph, we may conclude that at most $b/1000$ blocks $S_i$ are both narrow and impure. Since at least $\frac{999}{1000}b$ blocks are narrow, at least $\frac{998}{1000}b$ of the $b$ blocks are both narrow and pure, and Lemma 6.2 is proved.

At this point we have shown that at least $\frac{998}{1000}b$ blocks are both narrow and pure. Let $\text{pure}_1 < \text{pure}_2 < \cdots < \text{pure}_b$ be the indices of the pure blocks, where from the above lemma we have $b' \geq \frac{998}{1000}b$. To conclude the proof we now show that if there are so many pure blocks, then the error of $\text{sign}(v \cdot x)$ must exceed $2\varepsilon$.

The following terminology will be useful: Given an index $\kappa \in [n-1]$ we define the “upshift” $u_p(\kappa)$ to be $u_p(\kappa) = \kappa + 1$. For a set $S \subset [n]$ we define $u_p(S)$ to be the set

\[
u_p(S) = \{ j + 1 : j \in S \}.
\]

It is clear that $|u_p(S)| = |S|$ for all $S$, and that if a $\rho$ fraction of $S$ is even (odd), then a $\rho$ fraction of $u_p(S)$ is odd (even).

Consider any $\ell \in \{1, \ldots, b'\}$ for which $S_{\text{pure}_\ell}$ is a pure even block. (There are at least $\frac{4b}{100}$ such $\ell$‘s, since half of all indices are odd, half are even, and 99.8% of all indices belong to a pure block.) We say that $S_{\text{pure}_\ell}$ is upshift-decreasing if at least $\frac{45}{100}$ of the elements $j \in S_{\text{pure}_\ell}$ are even and have $u_p(j) \in S_{\ell'}$ for some $\ell' < \text{pure}_\ell$, and we say that $S_{\text{pure}_\ell}$ is upshift-increasing if at least $\frac{45}{100}$ of the elements $j \in S_{\text{pure}_\ell}$ are even and have $u_p(j) \in S_{\ell'}$ for some $\ell' > \text{pure}_\ell$. Since (at least) 99.9% of the elements $j \in S_{\text{pure}_\ell}$ are even, and thus have $u_p(j)$ odd, at least 99.8% of the elements $j \in S_{\text{pure}_\ell}$ are even and have $u_p(j)$ in some block $S_k$ with $k \neq \text{pure}_\ell$, so $S_{\text{pure}_\ell}$ must be either upshift-decreasing or upshift-increasing.

We consider two cases.

\begin{itemize}
\item \text{Case I: at least half of all pure even blocks $S_{\text{pure}_\ell}$ are upshift-decreasing.} In this case, there are at least $\frac{4b}{200}$ pure even upshift-decreasing blocks $S_{\text{pure}_\ell}$.

For $S_{\text{pure}_\ell}$ a pure even upshift-decreasing block, let $G_{\text{pure}_\ell} \subset S_{\text{pure}_\ell}$ denote the set

\[
G_{\text{pure}_\ell} = \{ j \in S_{\text{pure}_\ell} : j \text{ is even and } u_p(j) \in S_{\ell'} \text{ for some } \ell' < \text{pure}_\ell \}
\]

so $|G_{\text{pure}_\ell}| \geq \frac{4b}{400} \approx \frac{b}{400}$ (since $|S_{\text{pure}_\ell}| \approx \frac{b}{400}$). Let $L_{\text{pure}_\ell}$ denote the lower half of the elements in $G_{\text{pure}_\ell}$, and let $U_{\text{pure}_\ell} = G_{\text{pure}_\ell} \setminus L_{\text{pure}_\ell}$ denote the upper half of the elements (so for every $\alpha \in L_{\text{pure}_\ell}$ and $\beta \in U_{\text{pure}_\ell}$ we have $\alpha < \beta$). We have $|L_{\text{pure}_\ell}|, |U_{\text{pure}_\ell}| \geq \frac{b}{100} \cdot \frac{b}{400}$.

Fix an $\ell$ such that $S_{\text{pure}_\ell}$ is a pure even upshift-decreasing block. Consider the set of all inputs $x = e_{i_1} + \cdots + e_{i_k} \in \{0,1\}^{n-k}$ for which $i_1, \ldots, i_{k-1}$ all belong to $L_{\text{pure}_\ell}$ and $i_k$ belongs to $u_p(U_{\text{pure}_\ell})$. By the cardinality bounds of the previous paragraph there are at least

\[
|u_p(U_{\text{pure}_\ell})| \cdot \left( \frac{|L_{\text{pure}_\ell}|}{k-1} \right) \geq \left( \frac{2^n}{100} \right) \cdot \left( \frac{2^n}{100} \right)
\]

possible such outcomes for $x$, so the probability that a random $x \in \{0,1\}^{n-k}$ is of this
sort is at least 
\[
\left(\frac{2n}{10b}\right) \cdot \left(\frac{n}{k}\right) > k \cdot \frac{2n}{10b} \cdot \frac{\left(\frac{2n}{10b} - (k - 2)\right)^{k}}{n^{k}} > k \cdot \frac{2}{10b} \cdot \left(\frac{2}{10b} - \frac{k - 2}{n}\right)^{k - 1}
\] 

For such an \( x \) we have that \( v_{i_1}, v_{i_2}, \ldots, v_{i_{k-1}} > 0 \) (since \( i_1, \ldots, i_{k-1} \) are even), \( v_{i_k} < 0 \) (since \( i_k \) is odd), and \( |v_{i_1}|, \ldots, |v_{i_{k-1}}| \geq |v_{i_k}| \) (since \( i_k \) belongs to \( S'_{\ell} \) for some \( \ell' < \text{pure}_{\ell} \) and \( i_1, \ldots, i_{k-1} \) all belong to \( S_{\text{pure}_{\ell}} \)). These conditions together give us \( \text{sign}(v \cdot (e_{i_1} + \cdots + e_{i_k})) = +1 \). But since we have \( i_k \in \text{up}(U_{\text{pure}_{\ell}}) \) and \( i_1, \ldots, i_{k-1} \in L_{\text{pure}_{\ell}} \), it must be the case that \( i_1, \ldots, i_{k-1} < i_k \); since \( i_k \) is odd this means \( DL(x) = -1 \), so \( \text{sign}(v \cdot x) \) is incorrect on such \( x \). Taking a union bound across all \( \frac{49}{200} b \) possibilities for \( \ell \) that make \( S_{\text{pure}_{\ell}} \), a pure even upshift-decreasing block, we get that overall

\[
\Pr_{x \in \{0,1\}^{n_k}} \left[ \text{sign}(v \cdot x) \neq DL(x) \right] \geq \frac{49}{200} b \cdot \frac{1}{2^{\Theta(k)} b^k}
\]

which is larger than \( 2\varepsilon \).

We now turn to the second case.

Case II: at least half of all pure even blocks \( S_{\text{pure}_{\ell}} \) are upshift-increasing. In this case there are at least \( \frac{49}{200} b \) pure even upshift-increasing blocks \( S_{\text{pure}_{\ell}} \). Recall that in an upshift-increasing block, at least \( \frac{1}{10} \) of the elements \( j \in S_{\text{pure}_{\ell}} \) are even and have \( \text{up}(j) \in S'_{\ell'} \) for some \( \ell' > \text{pure}_{\ell} \).

The analysis of this case is quite similar to that of Case I; the difference is that we consider a slightly different event. For \( S_{\text{pure}_{\ell}} \), a pure even upshift-increasing block, let \( G_{\text{pure}_{\ell}} \subset S_{\text{pure}_{\ell}} \) denote the set

\[
G_{\text{pure}_{\ell}} = \{ j \in S_{\text{pure}_{\ell}} : j \text{ is even and } \text{up}(j) \in S'_{\ell'} \text{ for some } \ell' > \text{pure}_{\ell} \}
\]

so \( |G_{\text{pure}_{\ell}}| \geq \frac{4}{10} \cdot \frac{n}{b^{\frac{1}{2}}} \). As before, let \( L_{\text{pure}_{\ell}} \) denote the lower half of the elements in \( G_{\text{pure}_{\ell}} \), and let \( U_{\text{pure}_{\ell}} = G_{\text{pure}_{\ell}} \setminus L_{\text{pure}_{\ell}} \) denote the upper half of the elements (so for every \( \alpha \in L_{\text{pure}_{\ell}} \) and \( \beta \in U_{\text{pure}_{\ell}} \) we have \( \alpha < \beta \)). As before, we have \( |L_{\text{pure}_{\ell}}|, |U_{\text{pure}_{\ell}}| \geq \frac{2}{10} \cdot \frac{n}{b^{\frac{1}{2}}} \).

Fix an \( \ell \) such that \( S_{\text{pure}_{\ell}} \) is a pure even upshift-increasing block. Consider the set of all inputs \( x = e_{i_1} + \cdots + e_{i_k} \in \{0,1\}^{n_k} \) for which \( i_1, \ldots, i_{k-1} \) all belong to \( \text{up}(L_{\text{pure}_{\ell}}) \) and \( i_k \) belongs to \( U_{\text{pure}_{\ell}} \). As in Case I the probability that a random \( x \in \{0,1\}^{n_k} \) is of this sort is at least \( \frac{1}{2^{\Theta(k)}} \cdot \frac{1}{b^{\frac{1}{2}}} \). For such an \( x \) we have that \( v_{i_k} > 0 \) (since \( i_k \) is even), \( v_{i_1}, \ldots, v_{i_{k-1}} < 0 \) (since \( i_1, \ldots, i_{k-1} \) are all odd), and \( |v_{i_1}|, \ldots, |v_{i_{k-1}}| \geq |v_{i_k}| \) (since \( i_1, \ldots, i_{k-1} \) belong to \( S_{\ell_1} \) and \( S_{\ell_2} \), respectively, for some \( \ell_1, \ell_2 > \text{pure}_{\ell} \), whereas \( A \) belongs to \( S_{\text{pure}_{\ell}} \)). These conditions together give that \( \text{sign}(v \cdot (e_{i_1} + \cdots + e_{i_k})) = -1 \). But since we have \( i_k \in U_{\text{pure}_{\ell}} \) and \( i_1, \ldots, i_{k-1} \in \text{up}(L_{\text{pure}_{\ell}}) \), it must be the case that \( i_k > i_1, \ldots, i_{k-1} \); since \( i_k \) is even this means \( DL(x) = +1 \), so \( \text{sign}(v \cdot x) \) is incorrect on such an \( x \). The rest of the argument (analyzing the probability) proceeds exactly as in Case I: taking a union bound across all \( \frac{49}{200} b \) possibilities for \( \ell \) that make \( S_{\text{pure}_{\ell}} \) a pure even upshift-increasing block, we get that overall

\[
\Pr_{x \in \{0,1\}^{n_k}} \left[ \text{sign}(v \cdot x) \neq DL(x) \right] \geq \frac{49}{200} b \cdot \frac{1}{2^{\Theta(k)} b^k}
\]

\footnote{Note that in Case I we had “\( \ell' < \text{pure}_{\ell} \)”, whereas now we have “\( \ell' > \text{pure}_{\ell} \)” in the definition of \( G_{\text{pure}_{\ell}} \).}

\footnote{Note the difference from Case I.}
which is larger than $2\varepsilon$. We are done in Case II, and done with the proof of Theorem 6.1.

7. An upper bound for approximating decision lists. At this point we have established that every halfspace over $\{0, 1\}^k$ can be $\varepsilon$-approximated using weight $k^{O(k/\varepsilon)}$, and that for the DL halfspace any $\varepsilon$-approximator must use weight $k^{\Theta(1)/\varepsilon^{1/(k-1)}-1}$. It is a natural goal to close the gap between these upper and lower bounds; while we have not yet succeeded in doing this, we give a detailed analysis of the DL halfspace and prove a stronger $k^{O(k/\sqrt{\varepsilon})}$ upper bound for it. This tells us that if the $k^{O(k/\varepsilon)}$ upper bound of Theorem 5.1 is in fact the “right answer,” then any lower bound proof establishing this must use a halfspace other than DL.

**Theorem 7.1.** Let $\varepsilon, k, n$ satisfy $\varepsilon = \omega(k^2/n)$. Then there is an $\varepsilon$-approximator for the function DL over $\{0, 1\}^n_k$ that has weight $k^{O(k/\sqrt{\varepsilon})}$.

**Proof.** Recall that the obvious halfspace representation for DL as

$$\text{sign}\left(\sum_{i=1}^{n} (-2)^i x_i\right)$$

has weight $2^n$. We first present a simple construction with an easy analysis that gives an $\varepsilon/2$-approximator of weight $k^{O(k/\varepsilon)}$ under distribution $D_2$ (this yields an $\varepsilon$-approximator over $\{0, 1\}^n_k$ by Observation 2 and our choice of $\varepsilon$). This of course only recovers the general result of Theorem 5.1, but then we will sharpen this DL-specific simple construction and analysis to prove the theorem.

We assume that $\varepsilon$ is of the form $1/\text{integer}$, and we define $r \overset{\text{def}}{=} k/\varepsilon$. Note that $r < n$ by the assumed lower bound on $\varepsilon$.

We partition $[n]$ into $r$ blocks $S_1, \ldots, S_r$ whose sizes are as nearly even as possible, i.e.,

$$S_1 = \{1, \ldots, |S_1|\}, \ldots, S_r = \{n - |S_r| + 1, \ldots, n\},$$

where there is a fixed value $s \approx n/r$ such that $|S_i| \in \{s, s+1\}$ for all $1 \leq i \leq r$.

For $j \in [n]$ let $b(j) \in [r]$ denote the index of the block $S_{b(j)}$ that contains $j$. For $1 \leq j \leq n$ let $w_j \overset{\text{def}}{=} (-1)^j(2k)^{b(j)}$. It is clear that $\max_{j \in [n]} |w_j| = (2k)^r = (2k)^{k/\varepsilon}$.

We claim that $\text{sign}(w \cdot x)$ is an $O(\varepsilon)$-approximator for $DL(x)$ over $D_2$. To establish this, consider an input $x = e_{i_1} + \cdots + e_{i_k}$ drawn from $D_2$; i.e., $(i_1, \ldots, i_k)$ is drawn uniformly from $[n]^k$. Let $b^*$ denote $\max \{bl(i_1), \ldots, bl(i_k)\}$. Since the weights increase by a factor of $2k$ between successive blocks, it is easy to see that if there is precisely one index $j \in [k]$ for which $bl(i_j) = b^*$, then $\text{sign}(w \cdot x) = (-1)^{\max \{i_1, \ldots, i_k\}}$ agrees with the value $DL(x)$. So we have that $\Pr_{x \sim D_2}[\text{sign}(w \cdot x) \neq DL(x)]$ is at most the probability that there are at least two distinct indices $j_1, j_2 \in [k]$ such that $bl(i_{j_1}) = bl(i_{j_2}) = b^*$.

It is clear that for each $\ell \in [r]$, the probability that both none of $bl(i_{j_1}), \ldots, bl(i_{j_k})$ lie in $[\ell + 1, \ldots, r]$ and at least two of $bl(i_{j_1}), \ldots, bl(i_{j_k})$ equal $\ell$ is at most

$$O(1) \cdot \left(\frac{\ell}{r}\right) k^2 \frac{k^2}{\ell^2}.$$

Summing over $\ell = 1, \ldots, r$, we get that $\Pr_{x \sim D_2}[\text{sign}(w \cdot x) \neq DL(x)]$ is at most

$$\sum_{\ell=1}^{r} O(1) \cdot \frac{k^2}{r^k} \cdot \ell^{k-2} = O\left(\frac{k}{r}\right) = O(\varepsilon)$$
by our choice of \( r = k/\varepsilon \). This concludes the initial simple construction and analysis.

We now build on the above simple construction to prove Theorem 7.1. The idea is to have the magnitude of the weights increase gradually within each block while keeping the sign of each weight correct as in the earlier construction. This lets us argue that in order for an input to be misclassified, it must have the “top two” bits that are set to 1 being quite close to each other, as well as a third input bit set to 1 that is also close to these top two. This more stringent condition lets us give a stronger bound on the probability of failure, which lets us use smaller weights to achieve an overall failure probability of \( \varepsilon \).

We now take \( r = k/\sqrt{\varepsilon} \). As before we may assume this is an integer which is less than \( n \). We define \( r \) blocks of variables \( S_1, \ldots, S_r \) and \( bl(\cdot) \) as before.

We define integer weights \( w_1, \ldots, w_n \) as follows. For each \( j \) the sign of \( w_j \) is \((-1)^j\).

The magnitude of the weights is defined as follows: First, \(|w_1| = (2k)^r\). If the first weight in block \( S_i \) (say its index is \( \alpha_i + 1 \)) has \(|w_{\alpha_i+1}| = C\), then the magnitudes of weights increase linearly in that block from \((2k)C\); i.e., for \( j \in \{1, \ldots, |S_i|\} \) we have

\[
|w_{\alpha_i+j}| = C + C \cdot \left( \frac{(2k-1) \cdot j}{|S_i|} \right),
\]

so the final weight in block \( S_i \) has magnitude \(|w_{\alpha_i+|S_i|}| = (2k)C\). If the final weight \( w_{\alpha_i+|S_i|} \) of block \( S_i \) has magnitude \((2k)C\), then the first weight \( w_{\alpha_i+|S_i|+1} = w_{\alpha_i+1} \) of the next block has magnitude \((4k^2)C\) (so there is a factor-of-\((2k)\) increase in the weights between each pair of successive blocks). It is clear that all weights are integers and that the largest one has magnitude \(|w_n| \leq (2k)^r \cdot (2k)^{2r} = k^{O(r)}\). The halfspace we consider is \( \text{sign}(w \cdot x) \).

Consider an input \( x = e_{i_1} + \cdots + e_{i_k} \) drawn from \( D_2 \), so \((i_1, \ldots, i_k)\) is drawn uniformly from \([n]^k\). As before let \( b^* \) denote \( \max\{bl(i_1), \ldots, bl(i_k)\} \). As before, the only way that it is possible for \( \text{sign}(w \cdot x) \) to disagree with \( DL(x) \) is if there is some \( \ell \in [r] \) such that both none of \( bl(i_1), \ldots, bl(i_k) \) lie in \([\ell + 1, \ldots, r]\) and at least two of \( bl(i_1), \ldots, bl(i_k) \) equal \( \ell \). (Our subsequent analysis will impose even more conditions that must be satisfied in order for \( \text{sign}(w \cdot x) \) to be incorrect on \( x \).)

Fix any \( \ell \in [r] \). The probability that both

- none of \( bl(i_1), \ldots, bl(i_k) \) lie in \([\ell + 1, \ldots, r]\)

and

- at least two of \( bl(i_1), \ldots, bl(i_k) \) equal \( \ell \)

is at most \( k^2 \) times the probability that both

- none of \( bl(i_1), \ldots, bl(i_k) \) lie in \([\ell + 1, \ldots, r]\)

and

- \( bl(i_1) = bl(i_2) = \ell \);

let us condition on this event. Let us write \( i_1 = \alpha_\ell + j_1 \) and \( i_2 = \alpha_\ell + j_2 \); we have that \( j_1, j_2 \) are selected independently and uniformly from \( \{1, \ldots, |S_\ell|\} \approx \{1, \ldots, n/r\} \).

This means that \(|w_{i_1}| - |w_{i_2}|\) is essentially distributed as

\[
|w_{\alpha_\ell+1} \cdot (2k-1) \cdot (j_1 - j_2) / |S_\ell|\]

(we have omitted ceiling operators for readability; it is easy to check that this omission does not significantly affect the subsequent analysis), and consequently \( x \) is classified incorrectly only if at least one of the \( k-2 \) values \(|w_{i_1}|_{j=3,\ldots,k} \) is at least \(|w_{\alpha_\ell+1} \cdot (2k-1) \cdot (j_1 - j_2) / |S_\ell|\).
for otherwise the cumulative effect of the other \( k - 2 \) weights would not be large enough to offset the effect of \( w_{i_1} \) and \( w_{i_2} \).

Let \( c \in \{0, 1, \ldots, k \} \) be such that \( |j_1 - j_2|/|S_\ell| \in ((2k)^{-c + 1}, 2k)^{-c} \). Since every possible outcome for \( |j_1 - j_2| \) (where \( j_1, j_2 \) are drawn independently from \( \{1, \ldots, |S_\ell|\} \)) has probability at most \( O(1)/|S_\ell| \), we have that for each \( c \) the value \( \Pr[|j_1 - j_2|/|S_\ell| \in ((2k)^{-c + 1}, 2k)^{-c}] \) is at most \( O((2k)^{-c}) \). Because the weights increase by a factor of 2\( k \) between successive blocks, this means that the only way that \( |w_{i_\ell}| \) can be at least \( |w_{\alpha + 1 \cdot J_\ell}| \) is if \( b(i_j) \) belongs to \( \{ \ell - c + 1, \ell - c, \ldots, \ell \} \) (recall that because of our conditioning we have \( b(i_j) \leq \ell \)). Because of the conditioning described earlier, for each fixed \( j \in \{3, \ldots, k\} \) this occurs with probability \( O(1 + c)/\ell \). Taking a union bound over \( k - 2 \) different \( j \)'s, the probability that any \( |w_{i_\ell}| \) is as large as would be necessary to cause an error is at most \( O((1 + c)/\ell) \).

Putting all the pieces together and summing over all possible values \( \ell = 1, \ldots, r \), we have that

\[
\Pr_{x \sim D_2} [\text{sign}(w \cdot x) \neq DL(x)] \leq \sum_{\ell=1}^{r} O(1) \cdot \left( \frac{\ell}{r} \right)^k \frac{k^2}{\ell^2} \cdot \sum_{c=0}^{\infty} O((2k)^{-c}) \cdot \frac{O((1+c)k)}{\ell} = O(1) \cdot \frac{k^3}{r^k} \sum_{\ell=1}^{r} \ell^{k-3} \sum_{c=0}^{\infty} \frac{1+c}{(2k)^{c}}
\]

which is \( O(\varepsilon) \) by our choice of \( r \). The theorem is proved.

**8. Conclusion.** We have studied exact and approximate representations of halfspaces over the Hamming ball \( \{0, 1\}^n \leq k \), giving upper and lower bounds on the weight of such representations. While our upper and lower bounds are fairly close, there are still several open questions that naturally suggest themselves for follow-up work. In particular, our Theorem 5.1 gives a weight upper bound of \( k^{O(k/\varepsilon)} \) which is independent of \( n \) but depends superexponentially on \( k \); we suspect that it may be possible to improve this dependence on \( k \). Even for fixed \( k \) there is a gap between our upper bound, which is exponential in \( \varepsilon^{-1} \), and our lower bound, which is exponential in \( \varepsilon^{-1/(k-1)} \). It would be interesting to close this gap.

Finally, a broader goal for future work is to explore the implications of our newly established weight bounds on the effectiveness of various margin-based learning algorithms over \( \{0, 1\}^n \leq k \).

**References**


